Modelling and reasoning about references

A language with dynamic allocation

 $\begin{aligned} \tau &::= \text{unit} \mid \text{int} \mid \sigma \text{ ref} \mid \tau \times \tau \mid \tau + \tau \mid \tau \to \mathbf{T}\tau \\ \sigma &::= \text{int} \mid \sigma \text{ ref} \\ \gamma &::= \tau \mid \mathbf{T}\tau \end{aligned}$

$$\begin{split} V &::= x \mid \underline{n} \mid \underline{\ell} \mid () \mid (V, V') \mid \operatorname{in}_{i}^{\tau} V \mid \operatorname{rec} f(x : \tau) : \tau' = M \\ M &::= V V' \mid \operatorname{let} x \Leftarrow M \operatorname{in} M' \mid \operatorname{val} V \mid \pi_{i} V \mid \operatorname{ref} V \mid !V \mid V := V' \\ \mid \operatorname{case} V \operatorname{of} \operatorname{in}_{1} x \Rightarrow M \ ; \ \operatorname{in}_{2} x \Rightarrow M' \\ \mid V = V' \mid V + V' \mid \operatorname{iszero} V \end{split}$$

Store types Δ map locations $\ell \in \mathbb{L}$ to storable types σ

$$\begin{split} (rec) & \frac{\Delta; \Gamma, x: \tau, f: \tau \to \mathbf{T}(\tau') \vdash M: \mathbf{T}(\tau')}{\Delta; \Gamma \vdash (\operatorname{rec} f(x:\tau): \tau' = M): \tau \to \mathbf{T}(\tau')} & (loc) \frac{\ell: \sigma \in \Delta}{\Delta; \Gamma \vdash \underline{\ell}: \sigma \operatorname{ref}} \\ & (app) \frac{\Delta; \Gamma \vdash V_1: \tau \to \mathbf{T}\tau' \quad \Delta; \Gamma \vdash V_2: \tau}{\Delta; \Gamma \vdash V_1 V_2: \mathbf{T}\tau'} \\ (let) & \frac{\Delta; \Gamma \vdash M_1: \mathbf{T}(\tau_1) \quad \Delta; \Gamma, x: \tau_1 \vdash M_2: \mathbf{T}(\tau_2)}{\Delta; \Gamma \vdash \operatorname{let} x \leftarrow M_1 \operatorname{in} M_2: \mathbf{T}(\tau_2)} & (val) \frac{\Delta; \Gamma \vdash V: \tau}{\Delta; \Gamma \vdash \operatorname{val} V: \mathbf{T}(\tau)} \\ & (eq) \frac{\Delta; \Gamma \vdash V_1: \sigma \operatorname{ref} \quad \Delta; \Gamma \vdash V_2: \sigma \operatorname{ref}}{\Delta; \Gamma \vdash V_1 = V_2: \mathbf{T}(\operatorname{unit} + \operatorname{unit})} & (deref) \frac{\Delta; \Gamma \vdash V: \sigma \operatorname{ref}}{\Delta; \Gamma \vdash V: \mathbf{T}\sigma} \\ (alloc) \frac{\Delta; \Gamma \vdash V: \sigma}{\Delta; \Gamma \vdash \operatorname{ref} V: \mathbf{T}(\sigma \operatorname{ref})} & (assign) \frac{\Delta; \Gamma \vdash V_1: \sigma \operatorname{ref} \quad \Delta; \Gamma \vdash V_2: \sigma}{\Delta; \Gamma \vdash V_1: = V_2: \mathbf{T}(\operatorname{unit})} \end{split}$$

Continuation-based termination relation

 Σ , let $x \Leftarrow M$ in $K \downarrow$

$$\frac{\Delta; x: \tau \vdash M: \mathbf{T}\tau' \quad \Delta; \vdash K: (y:\tau')^{\top}}{\Delta; \vdash \operatorname{let} y \Leftarrow M \text{ in } K: (x:\tau)^{\top}}$$

States Σ map locations to $\mathbb{Z} + \mathbb{L}$

How to model such a language?

- Nondeterminism and invariance
- Encapsulation
- Functor categories
- FM cpos

Semantics of types

 $\begin{bmatrix} \text{unit} \end{bmatrix} = 1 \qquad \begin{bmatrix} \tau_1 \times \tau_2 \end{bmatrix} = \begin{bmatrix} \tau_1 \end{bmatrix} \times \begin{bmatrix} \tau_2 \end{bmatrix} \\ \begin{bmatrix} \text{int} \end{bmatrix} = \mathbb{Z} \qquad \begin{bmatrix} \tau_1 + \tau_2 \end{bmatrix} = \begin{bmatrix} \tau_1 \end{bmatrix} + \begin{bmatrix} \tau_2 \end{bmatrix} \\ \begin{bmatrix} \sigma \text{ ref} \end{bmatrix} = \mathbb{L} \qquad \begin{bmatrix} \tau_1 \to \mathbf{T} \tau_2 \end{bmatrix} = \begin{bmatrix} \tau_1 \end{bmatrix} \Rightarrow \mathbf{T} \begin{bmatrix} \tau_2 \end{bmatrix} \\ \mathbf{T} D = (\mathbb{S} \Rightarrow D \Rightarrow \mathbb{O}) \multimap (\mathbb{S} \Rightarrow \mathbb{O})$

 $\mathbb{S} = \mathbb{L} \Rightarrow (\mathbb{Z} + \mathbb{L})$

$$\llbracket \Delta; \Gamma \vdash \underline{\ell} : \sigma \operatorname{ref} \rrbracket \rho = \ell$$

$$\begin{bmatrix} \Delta; \Gamma \vdash \det x \Leftarrow M_1 \text{ in } M_2 : \mathbf{T}\tau_2 \end{bmatrix} \rho \ k \ S = \\ \begin{bmatrix} \Delta; \Gamma \vdash M_1 : \mathbf{T}\tau_1 \end{bmatrix} \rho \ (\lambda S' : \mathbb{S}.\lambda d : \llbracket \tau_1 \rrbracket. \llbracket \Delta; \Gamma, x : \tau_1 \vdash M_2 : \mathbf{T}\tau_2 \rrbracket \rho \llbracket x \mapsto d \rrbracket k \ S') \ S \end{bmatrix}$$

 $\llbracket \Delta; \Gamma \vdash \operatorname{val} V : \mathbf{T}\tau \rrbracket \rho \ k \ S = k \ S \ (\llbracket \Delta; \Gamma \vdash V : \tau \rrbracket \rho)$

$$\llbracket \Delta; \Gamma \vdash !V : \mathbf{T}\sigma \rrbracket \rho \ k \ S \ = \begin{cases} k \ S \ v \ \text{if} \ S(\llbracket \Delta; \Gamma \vdash V : \sigma \ \text{ref} \rrbracket \rho) = in_{\llbracket \sigma \rrbracket } v \\ \bot \quad \text{otherwise} \end{cases}$$

$$\begin{bmatrix} \Delta; \Gamma \vdash V_1 := V_2 : \operatorname{Tunit} & \rho \ k \ S = \\ k \ S[(\llbracket \Delta; \Gamma \vdash V_1 : \sigma \operatorname{ref} & \rho) \mapsto in_{\llbracket \sigma \rrbracket}(\llbracket \Delta; \Gamma \vdash V_2 : \sigma & \rho)] * \end{cases}$$

 $\llbracket \Delta; \Gamma \vdash \operatorname{ref} V : \mathbf{T}\sigma \operatorname{ref} \rrbracket \rho \ k \ S = k \ S[\ell \mapsto in_{\llbracket \sigma \rrbracket}(\llbracket \Delta; \Gamma \vdash V : \sigma \rrbracket \rho)] \ \ell$ for some/any $\ell \not\in supp(\lambda \ell' . k \ S[\ell' \mapsto in_{\sigma}(\llbracket \Delta; \Gamma \vdash V : \sigma \rrbracket \rho)] \ \ell').$

 $\begin{bmatrix} \Delta; \Gamma \vdash (\operatorname{rec} f \ x = M) : \tau \to \mathbf{T}\tau' \end{bmatrix} \rho = fix(\lambda f' : \llbracket \tau \to \mathbf{T}\tau' \rrbracket . \lambda x' : \llbracket \tau \rrbracket . \llbracket \Delta; \Gamma, f : \tau \to \mathbf{T}\tau', x : \tau \vdash M : \mathbf{T}\tau' \rrbracket \rho[f \mapsto f', x \mapsto x'])$

Soundness and adequacy

If $\Delta; \vdash M : \mathbf{T}\tau, \Delta; \vdash K : (x : \tau)^{\tau}, \Sigma : \Delta \text{ and } S \in \llbracket \Sigma \rrbracket$ then

 $\Sigma, \text{let } x \leftarrow M \text{ in } K \downarrow \iff [\![\Delta; \vdash M : \mathbf{T}\tau]\!] \{\} [\![\Delta; \vdash K : (x : \tau)^\top]\!]^{\mathcal{K}} S = \top.$

as a corollary

 $\llbracket\Delta; \Gamma \vdash G_1 : \gamma \rrbracket = \llbracket\Delta; \Gamma \vdash G_2 : \gamma \rrbracket \text{ implies } \Delta; \Gamma \vdash G_1 =_{\mathrm{ctx}} G_2 : \gamma$

(in)equivalences

 $\Delta; \Gamma \vdash V_1 : \sigma_1 \quad \Delta; \Gamma \vdash V_2 : \sigma_2 \quad \Delta; \Gamma, x : \sigma_1 \operatorname{ref}, y : \sigma_2 \operatorname{ref} \vdash N : \mathbf{T}\tau$

 $\Delta; \Gamma \vdash \frac{\det x \leftarrow \operatorname{ref} V_1 \text{ in } (\det y \leftarrow \operatorname{ref} V_2 \text{ in } N)}{\det y \leftarrow \operatorname{ref} V_2 \text{ in } (\det x \leftarrow \operatorname{ref} V_1 \text{ in } N) : \mathbf{T}\tau \bigcirc}$

$$\frac{\Delta; \Gamma \vdash V : \sigma \quad \Delta; \Gamma \vdash N : \mathbf{T}\tau}{\Delta; \Gamma \vdash \det x \leftarrow \operatorname{ref} V \operatorname{in} N \ =_{\operatorname{ctx}} \ N : \mathbf{T}\tau} \stackrel{X \notin fvN}{\Longrightarrow}$$

A Parametric Logical Relation

- Partially ordered set of parameters *p*
- Parameter-indexed relations

 $\forall p. \mathcal{R}_{\mathbb{S}}(p) \subseteq \mathbb{S} \times \mathbb{S}$

$\forall p. \forall \gamma. \mathcal{R}_{\gamma}(p) \subseteq \llbracket \gamma \rrbracket \times \llbracket \gamma \rrbracket$

- Show denotation of each term related to itself
- Corollary: terms with related denotations are contextually equivalent

Accessibility maps

 Support turns out not to help in defining "the part of the store about which a relation depends":

 $\{(S_1, S_2) \mid \exists \ell, S_1 \ell = 0 = S_2 \ell\}$

An accessibility map A is a function from \mathbb{S} to finite subsets of \mathbb{L} , such that:

 $\forall S, S' \in \mathbb{S}, (\forall \ell \in AS, S\ell = S'\ell) \Longrightarrow A(S) = A(S')$

The subtyping ordering <: is defined as:

$$A <: A' \iff \forall S, A(S) \supseteq A'(S)$$

Accessibility maps from state types

If Δ is a state type, then $\operatorname{Acc}_{\Delta} : \mathbb{S} \to \mathbb{P}_{fin}(\mathbb{L})$ is defined by $\operatorname{Acc}_{\Delta}(S) = \bigcup_{(\ell:\sigma)\in\Delta} \operatorname{Acc}(\ell,\sigma,S)$ where $\operatorname{Acc}(\ell,\operatorname{int},S) \stackrel{def}{=} \{\ell\}$ and

$$\mathsf{Acc}(\ell, \sigma \mathsf{ref}, S) \stackrel{def}{=} \{\ell\} \cup \begin{cases} \mathsf{Acc}(\ell', \sigma, S) & \text{if } S \, \ell = \mathsf{in}_{\mathbb{L}} \ell' \\ \emptyset & \text{otherwise} \end{cases}$$

If A is an accessibility map, we define $S \sim S' : A$ to mean $\forall \ell \in A(S), S\ell = S'\ell$.

Finitary state relations

A finitary state relation r is a pair $\langle |r|, A_r \rangle$ where $|r| \subseteq \mathbb{S} \times \mathbb{S}$ and A_r is an accessibility map, subject to the following saturation condition: if $S_1 \sim S'_1 : A_r$ and $S_2 \sim S'_2 : A_r$ then $(S_1, S_2) \in |r| \iff (S'_1, S'_2) \in |r|$.

Given two finitary state relations, $r_1 = \langle |r^1|, A^1 \rangle$ and $r_2 = \langle |r^2|, A^2 \rangle$, define

$$r^1 \otimes r^2 \stackrel{def}{=} \langle |r^1 \otimes r^2|, A^1 \wedge A^2 \rangle$$

where

$$(S_1, S_2) \in |r^1 \otimes r^2| \iff \begin{cases} (S_1, S_2) \in |r^1| \cap |r^2| \\ \forall i \in \{1, 2\}, A^1(S_i) \cap A^2(S_i) = \emptyset \end{cases}$$

Parameters

A parameter is a pair (Δ, r) , where Δ is a state type and r is a finitary relation; we will abbreviate this to Δr . If Δr is a parameter, we define the binary relation on states $\mathcal{R}_{\mathbb{S}}(\Delta r) \stackrel{def}{=} |id_{\Delta} \otimes r|$ and define the partial order \triangleright on parameters by

 $\Delta r \rhd \Delta' r' \iff (\Delta \supseteq \Delta') \land (\exists r'', r = r' \otimes r'')$

Logical Relation

$$\begin{aligned} \mathcal{R}_{\text{unit}}(\Delta r) &= \{(*,*)\} \\ \mathcal{R}_{\text{int}}(\Delta r) &= \{(n,n) \mid n \in N\} \\ \mathcal{R}_{\sigma \text{ ref}}(\Delta r) &= \{(\ell,\ell) \mid (\ell : \sigma) \in \Delta\} \\ \mathcal{R}_{\tau \to T\tau'}(\Delta r) &= \\ \{(f_1,f_2) \mid \forall \Delta' r' \rhd \Delta r, (v_1,v_2) \in \mathcal{R}_{\tau}(\Delta' r'), (f_1v_1,f_2,v_2) \in \mathcal{R}_{T\tau'}(\Delta' r')\} \end{aligned}$$

For continuations, we define $\mathcal{R}_{\tau^{\top}}(\Delta r)$ to be

$$\{ (k_1, k_2) \mid \forall \Delta' r' \rhd \Delta r, (v_1, v_2) \in \mathcal{R}_{\tau}(\Delta' r'), (S_1, S_2) \in \mathcal{R}_{\mathbb{S}}(\Delta' r'), \\ k_1 S_1 v_1 = k_2 S_2 v_2 \}$$

and for computations, $\mathcal{R}_{\mathrm{T} au}(\Delta r)$ is defined as

$$\{ (f_1, f_2) \mid \forall \Delta' r' \rhd \Delta r, (k_1, k_2) \in \mathcal{R}_{\tau^{\top}}(\Delta' r'), (S_1, S_2) \in \mathcal{R}_{\mathbb{S}}(\Delta' r'), \\ f_1 k_1 S_1 = f_2 k_2 S_2 \}$$

Why?

- Fundamental Lemma:
- If Δ ; $\Gamma \vdash G : \gamma$, then

 $\forall r. (\llbracket \Delta; \Gamma \vdash G : \gamma \rrbracket, \llbracket \Delta; \Gamma \vdash G : \gamma \rrbracket) \in \mathcal{R}_{\Gamma \vdash \gamma}(\Delta r).$

• Soundness of relational reasoning: If Δ ; $\Gamma \vdash G_i : \gamma$ for i = 1, 2 and $(\llbracket \Delta; \Gamma \vdash G_1 : \gamma \rrbracket, \llbracket \Delta; \Gamma \vdash G_2 : \gamma \rrbracket) \in \mathcal{R}_{\Gamma \vdash T\tau}(\Delta \top)$ then $\Delta; \Gamma \vdash G_1 =_{ctx} G_2 : \gamma$.

Examples

- The garbage collection rule from earlier
- All the Meyer-Sieber examples, e.g

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\begin{array}{l} \operatorname{let} x \Leftarrow \operatorname{ref} \underline{0} \text{ in} \\ \operatorname{let} almost\_add2 \Leftarrow \lambda z. \text{if } z = x \\ & \text{then } x := 1 \\ & \text{else let } y \Leftarrow !x \text{ in let } y' \Leftarrow y + 2 \text{ in } x := y' \text{in} \\ & p(almost\_add2); \\ & \text{let } y \Leftarrow !x \text{ in} \\ & \text{if } !x \text{ mod } 2 = 0 \text{ then diverge}_{\text{unit}} \text{ else val ()} \end{array}
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Examples

• Pointers between hidden and visible parts:

let $x \Leftarrow ref 0$ in let $y \Leftarrow ref x$ in p x; let $z \Leftarrow ! y$ in if z = x then diverge_{unit} else val ()

 Some very artificial encodings of crypto a la Sumii and Pierce

Non-examples 😕

$$\begin{split} M = & \operatorname{let} x \Leftarrow \operatorname{ref0in} \\ & p(\lambda_- . \, x := 1; \ 0); \\ & \operatorname{let} y \Leftarrow ! x \operatorname{in} \\ & \operatorname{if} \operatorname{iszero} y \ \operatorname{then} \ \operatorname{val}() \ \operatorname{else} \ \operatorname{diverge}_{\operatorname{unit}} \end{split}$$

$$N = p (\lambda_{-}. diverge_{int})$$

snapback $f k S = f * (\lambda S' \cdot \lambda n \cdot k S n) S$

Garbage Collection If x is not free in M, and $\Delta; \Gamma \vdash M : \mathbf{T}\tau$, then

 $\Gamma \vdash \operatorname{let} x \Leftarrow \operatorname{ref} V \operatorname{in} M =_{\operatorname{ctx}} M : \mathbf{T}\tau$

We prove that $\llbracket \text{let } x \Leftarrow \text{ref } V \text{ in } M \rrbracket$ and $\llbracket M \rrbracket$ are related by $\mathcal{R}_{\Gamma \vdash \mathbf{T}_{\tau}}(\Delta \top)$, and we conclude using Theorem 17. Let $\Delta' r' \triangleright \Delta \top$ be a parameter and $(\rho_1, \rho_2) \in \mathcal{R}_{\Gamma}(\Delta' r')$. We need to prove that $(\llbracket \text{let } x \Leftarrow \text{ref } V \text{ in } M \rrbracket \rho_1, \llbracket M \rrbracket \rho_2) \in \mathcal{R}_{\mathbf{T}_{\tau}}(\Delta' r')$. Let $\Delta'' r'' \triangleright \Delta' r', \ (k_1, k_2) \in \mathcal{R}_{\tau^{\top}}(\Delta'' r'')$ and $(S_1, S_2) \in \mathcal{R}_{\mathbb{S}}(\Delta'' r'')$. We have to prove that

$$\llbracket \operatorname{tref} V \operatorname{in} M \rrbracket \rho_1 k_1 S_1 = \llbracket M \rrbracket \rho_2 k_2 S_2$$

For $\ell \notin supp(\lambda \ell'.k_1S_1[\ell' \to \llbracket V \rrbracket \rho]\ell')$

 $\llbracket \operatorname{let} x \leftarrow \operatorname{ref} V \text{ in } M \rrbracket \rho_1 k_1 S_1 = \llbracket M \rrbracket \rho_1 k_1 S_1 [\ell \to \llbracket V \rrbracket \rho_1]$

because x is not free in M. Since we can pick any such ℓ , we actually choose one also out of $\operatorname{Acc}_{\Delta''}(S_i) \cup A_{r''}(S_i)$ for i = 1, 2. By the fundamental lemma, $\llbracket M \rrbracket$ is related to itself by $\mathcal{R}_{\Gamma \vdash \mathbf{T}_{\tau}}(\Delta \top)$, so if we prove that $(S_1[\ell \to \llbracket V \rrbracket \rho_1], S_2) \in \mathcal{R}_{\mathbb{S}}(\Delta''r'')$ we are done.

First, since $\ell \notin \operatorname{Acc}_{\Delta''}(S_i)$, $(S_1[\ell \to \llbracket V \rrbracket \rho_1], S_2) \in id_{\Delta''}$, and since $\ell \notin A_{r''}(S_i)$, $(S_1[\ell \to \llbracket V \rrbracket \rho_1], S_2) \in r''$. By definition of accessibility maps, $\operatorname{Acc}_{\Delta''}$ and $A_{r''}$ are unchanged, so they still do not overlap, which concludes the proof.