# CIS 313: Intermediate Data Structure

sixth slide

#### expected behavior

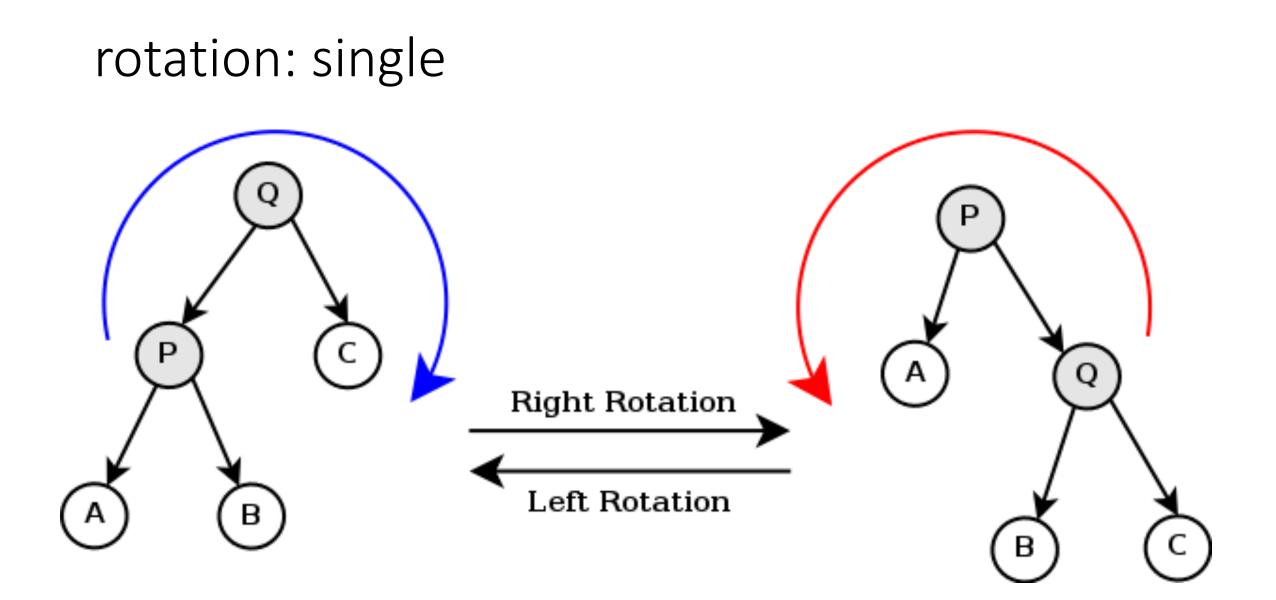
- if list a is chosen randomly from among all n! permutations
- how long does "for i=1 to n T.insert(a<sub>i</sub>)" take?
- worst case: O(n<sup>2</sup>)
- want to argue: on average O(n *lg* n)
- main fact: expected search time (1+I/n) in BST built from randomly chosen permutation is  $2 \cdot \ln(n+1) + O(1) \approx 1.38 \log_2 n + O(1)$

#### observations

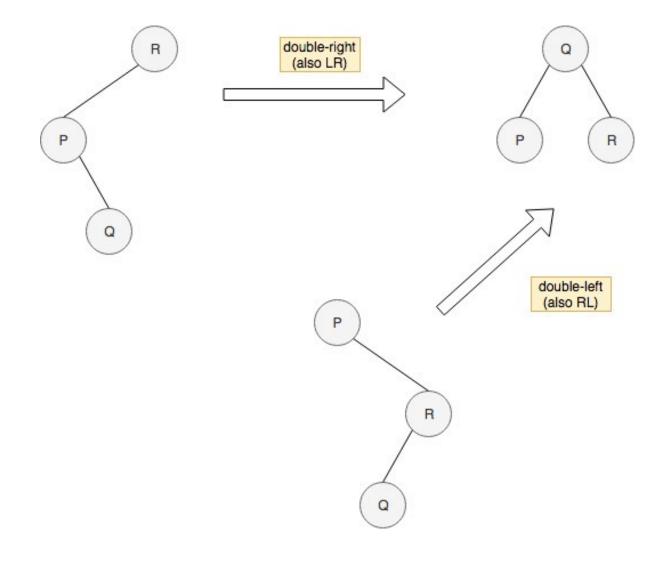
- this does not bound the height of the tree
- exercise 12.4-2, p 303: describe a binary search tree on n nodes such that the average depth of a node in the tree is  $\Theta(\lg n)$  but the height of the tree is  $\omega(\lg n)$
- stronger result: height of randomly built BST is is  $\Theta(\lg n)$
- new goal: maintain BST whose height is is  $\Theta(\lg n)$  in the worst case
- self balancing search trees: AVL, red-black, B-trees

# balanced tree

- not realistic to expect perfectly balanced tree
- one attempt (not common): weight-balance, where the number of nodes in left and right subtrees of any node must be close to each other
- better: *height-balance*, the height of the left and right subtrees must be close
- AVL: differ by one
- red-black: differ by factor of two
- balance maintained by rotations



#### rotations: double



Composed from two single rotations.

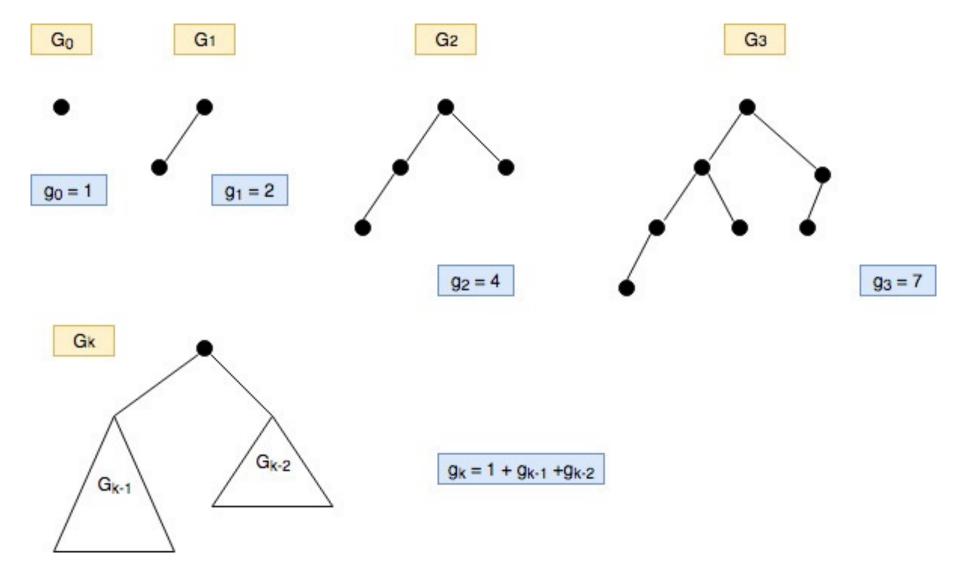
#### AVL trees

- (not in text)
- named after inventors Adelson-Velskii and Landis
- store at each node the balance factor:
  - bf(p) = height(p.lchild) height(p.rchild)
  - requirement: for every node p, bf(p) equals -1, 0, or 1
- requires two bits extra storage at each node

# AVL height is O(*lg*n)

- let G<sub>k</sub> be an AVL tree (shape) of height k with the fewest number of nodes
- $G_k$  can be constructed inductively as a node with a  $G_{k-1}$  left child and a  $G_{k-2}$  right child
- define  $g_k$  to be the number of nodes in a  $G_k$  tree
- $g_0 = 1$ ,  $g_1 = 2$ ,  $g_k = 1 + g_{k-1} + g_{k-2}$
- sequence: 1, 2, 4, 7, 12, 20
- fact:  $g_k = F_{k+3} 1$  ("easy" to prove with induction)

# trees G<sub>k</sub> and values g<sub>k</sub>



### AVL tree height: the punchline

• if n is the number of nodes in an AVL tree of height H then

• we know 
$$F_k = \left[ \frac{\varphi^k}{\sqrt{5}} \right]$$
, where  $\varphi = \frac{1+\sqrt{5}}{2} \approx 1.618$   
•  $\lg F_{H+3} \ge \lg \frac{\varphi^{H+3}}{\sqrt{5}} - 1 = (H+3) \lg \varphi - \lg \sqrt{5} - 1 \ge (H+3) \lg \varphi - 4$ 

 $n \geq q_{H} = F_{H+3} - 1$ 

- so  $(H + 3) \lg \varphi 4 \le \lg F_{H+3} \le \lg (n + 1)$  (take log of both sides of top line)
- moving terms around:  $H \leq \frac{\lg(n+1)+4}{\lg \varphi} 3 \approx 1.44 \lg(n+1) + O(1)$

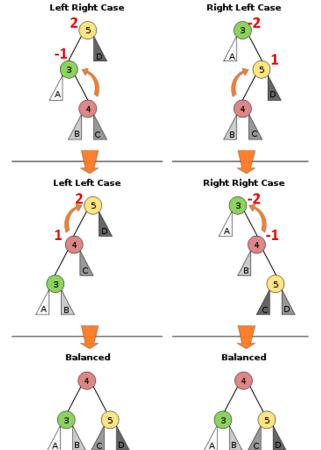
# AVL insertion

- insert node as with a BST (add it to a null pointer)
- update balance factors along path from new node to root
- the balance factors of some nodes may in violation: 2 or -2
- find the *critical node*: the lowest out of balance node
- perform the appropriate rotation
- note: this will affect the balance factors of nodes above it
- total insertion time O(*lg* n)

# AVL insertion

#### Four Possible Cases

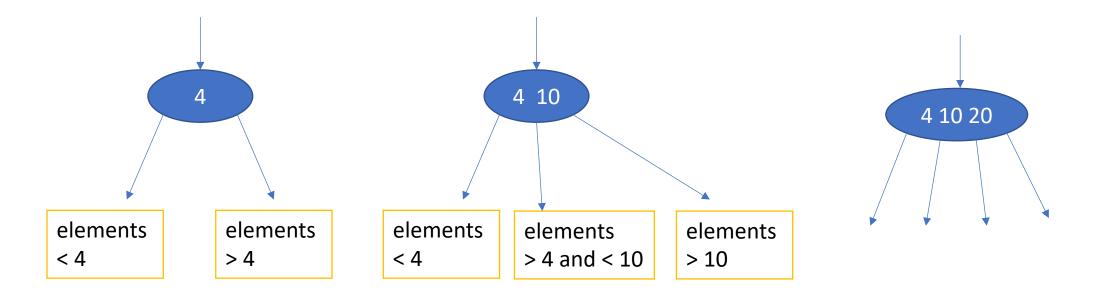
bf(x) = +2 and bf(x.left) = 1
rightRotate(x)
bf(x) = +2 and bf(x.left) = -1
leftRotate(x.left)
rightRotate(x)
bf(x) = -2 and bf(x.right) = -1
leftRotate(x)
bf(x) = -2 and bf(x.right) = 1
rightRotate(x.right)
leftRotate(x)



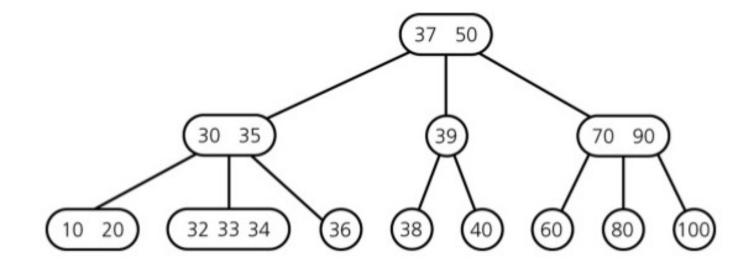
#### 2-3 and 2-3-4 trees

- quick intro here, we will return to them later as B-trees
- a 2-3 tree is a B-tree of order 3 (see ex 18-2, p 503, of text)
- these use multi-way search nodes
- must be perfectly balanced: all paths from the root to a null node have the same length
- insertions cause splits rather than rotations
- *important*: red-black trees (our real focus) are a binary implementation of 2-3-4 trees

### multiway search nodes



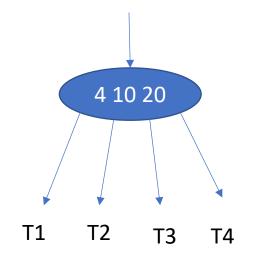
# example

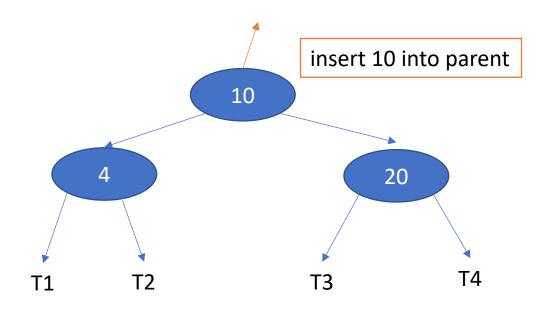


# insertion: splitting nodes

- can split a node when it is full or has overflowed
- splitting on insertion can be bottom-up
  - put node at bottom of tree, if over-flow, split on the way up
- or top-down
  - when looking for insertion point, if full node seen, split it
- most B-tree implementations use bottom up (less space)

# splitting a full node

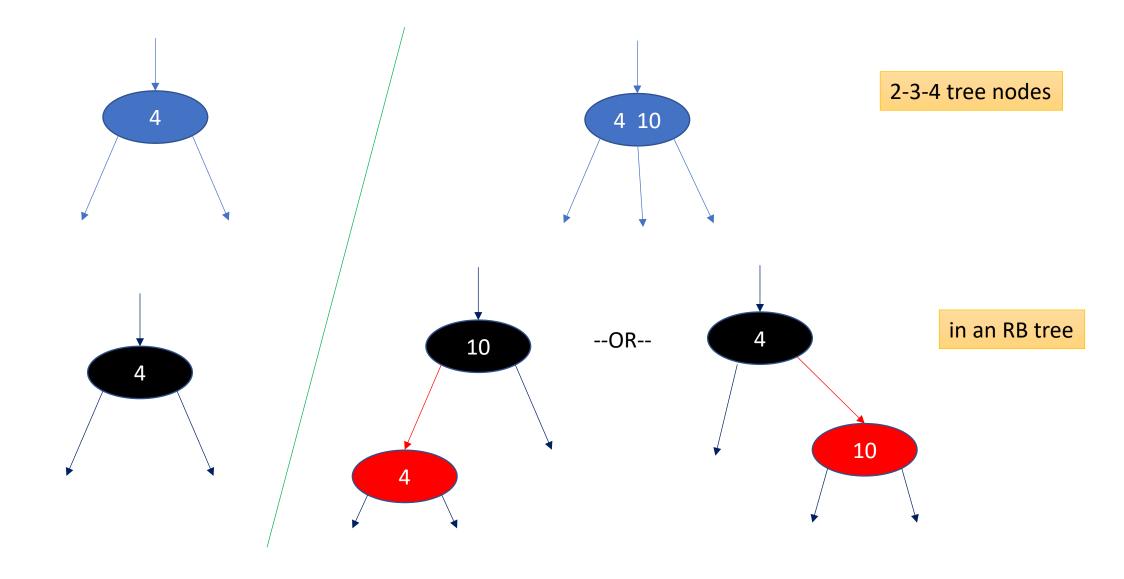




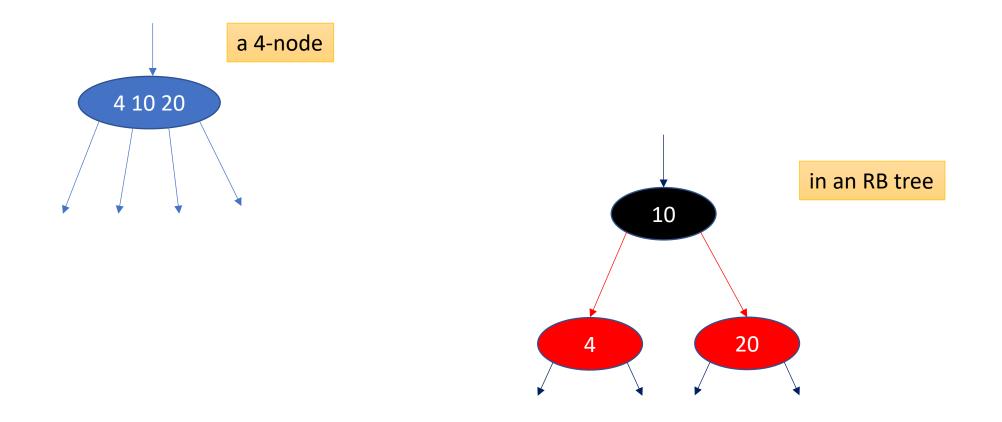
#### red-black trees and 2-3-4 trees

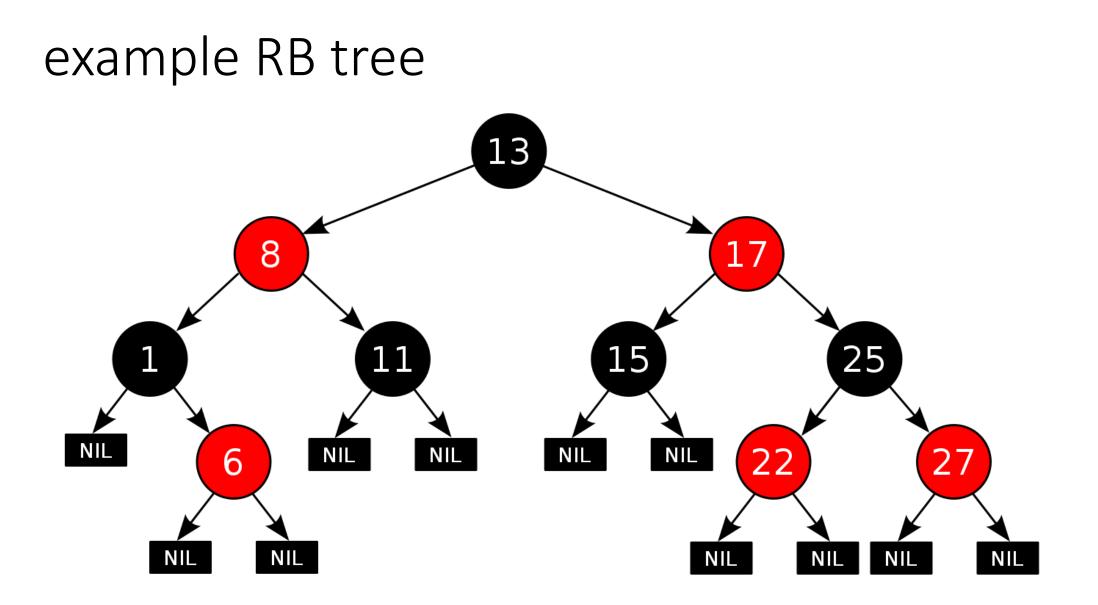
- a 2-3-4 tree node would need up to 4 child pointers
- frequently unused so waste of space
- red-black tree is binary tree implementation of 2-3-4 tree
- uses rotations to handle the splits
- need one bit to indicate color
  - descending the tree, black means "new node"
  - red means "belong to parent"
- Java uses RB trees in the TreeMap class (https://docs.oracle.com/javase/7/docs/api/java/util/TreeMap.html)

#### 2-3-4 nodes as RB nodes (2- and 3-nodes)

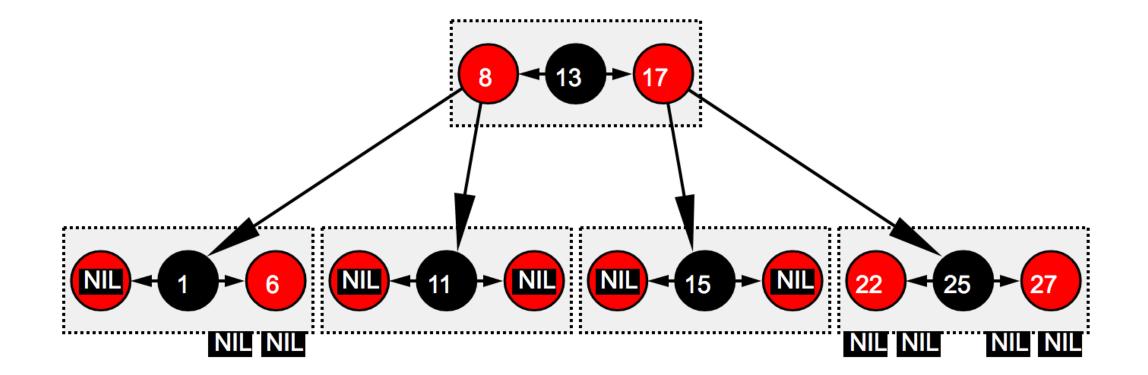


# 2-3-4 nodes as RB nodes (4-nodes)





#### viewed as 2-3-4 tree



# red-black tree rules

- 1. every node is either red or black
- 2. the root is black
- 3. every leaf (null) is black
- 4. if a node is red, both of its children are black
- 5. for each node, all simple paths from the node to descendant leaves contain the same number of black nodes