Multithreaded Programming in Cilk — LECTURE 1

July 13, 2006

Multithreaded Programming in *Cilk*

LECTURE 1

Charles E. Leiserson

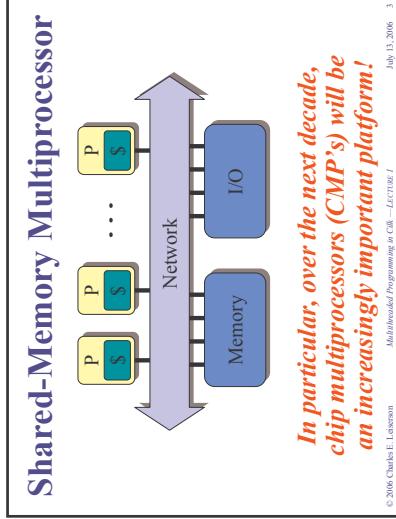*Supercomputing Technologies Research Group*
Computer Science and Artificial Intelligence Laboratory
Massachusetts Institute of Technology

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Cilk

A C language for programming dynamic multithreaded applications on shared-memory multiprocessors.

Example applications:

- virus shell assembly
- graphics rendering
- *n*-body simulation
- heuristic search
- dense and sparse matrix computations
- friction-stir welding simulation
- artificial evolution

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Shared-Memory Multiprocessor

In particular, over the next decade, chip multiprocessors (CMP's) will be an increasingly important platform!

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Cilk Is Simple

- Cilk extends the C language with just a *handful* of keywords.
- Every Cilk program has a *serial semantics*.
- Not only is Cilk fast, it provides *performance guarantees* based on performance abstractions.
- Cilk is *processor-oblivious*.
- Cilk's *provably good* runtime system automatically manages low-level aspects of parallel execution, including protocols, load balancing, and scheduling.
- Cilk supports *speculative* parallelism.

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Minicourse Outline

- **LECTURE 1**
  Basic Cilk programming: Cilk keywords, performance measures, scheduling.
- **LECTURE 2**
  Analysis of Cilk algorithms: matrix multiplication, sorting, tableau construction.
- **LABORATORY**
  Programming matrix multiplication in Cilk
  — *Dr. Bradley C. Kuszmaul*
- **LECTURE 3**
  Advanced Cilk programming: speculative computing, mutual exclusion, race detection.

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LECTURE 1

- **Basic Cilk Programming**
- **Performance Measures**
- **Parallelizing Vector Addition**
- **Scheduling Theory**
- **A Chess Lesson**
- **Cilk's Scheduler**
- **Conclusion**

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Fibonacci

```
int fib (int n) {
  if (n<2) return (n);
  else {
    int x,y;
    x = fib(n-1);
    y = fib(n-2);
    return (x+y);
  }
}
```

C elision

Cilk code

```
cilk int fib (int n) {
  if (n<2) return (n);
  else {
    int x,y;
    x = spawn fib(n-1);
    y = spawn fib(n-2);
    sync;
    return (x+y);
  }
}
```

Cilk is a *faithful* extension of C. A Cilk program's *serial elision* is always a legal implementation of Cilk semantics. Cilk provides *no* new data types.

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Basic Cilk Keywords

```
cilk int fib (int n) {
  if (n<2) return (n);
  else {
    int x,y;
    x = spawn fib(n-1);
    y = spawn fib(n-2);
    sync;
    return (x+y);
  }
}
```

Identifies a function as a *Cilk procedure*, capable of being spawned in parallel.

The named *child* Cilk procedure can execute in parallel with the *parent* caller.

Control cannot pass this point until all spawned children have returned.

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Dynamic Multithreading

```
cilk int fib (int n) {
  if (n<2) return (n);
  else {
    int x,y;
    x = spawn fib(n-1);
    y = spawn fib(n-2);
    sync;
    return (x+y);
  }
}
```

Example: fib(4)

"Processor oblivious"

The *computation dag* unfolds dynamically.

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Multithreaded Computation

initial thread *final thread* *return edge*
continue edge *spawn edge*

- The dag $G = (V, E)$ represents a parallel instruction stream.
- Each vertex $v \in V$ represents a *(Cilk) thread*: a maximal sequence of instructions not containing parallel control (**spawn**, **sync**, **return**).
- Every edge $e \in E$ is either a *spawn* edge, a *return* edge, or a *continue* edge.

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Cactus Stack

Cilk supports C's rule for pointers: A pointer to stack space can be passed from parent to child, but not from child to parent. (Cilk also supports **malloc**.)

Views of stack

Cilk's *cactus stack* supports several views in parallel.

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LECTURE 1

- **Basic Cilk Programming**
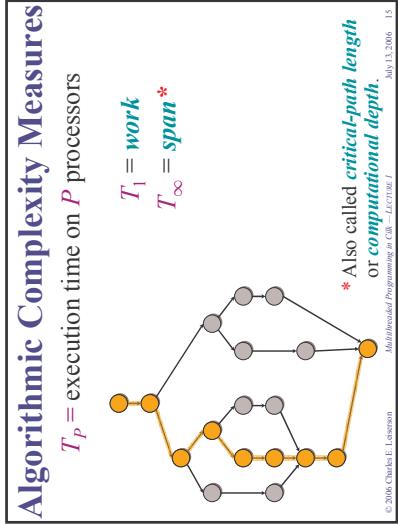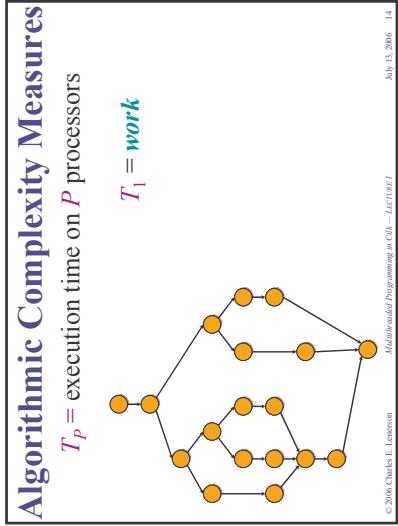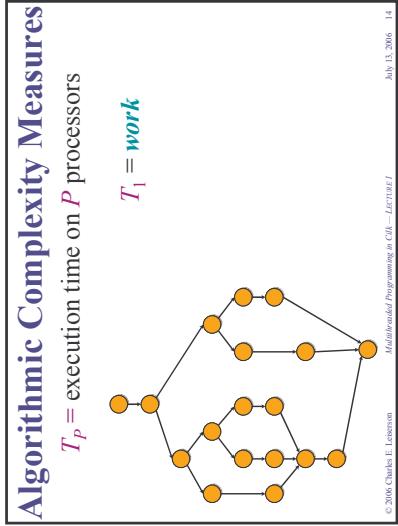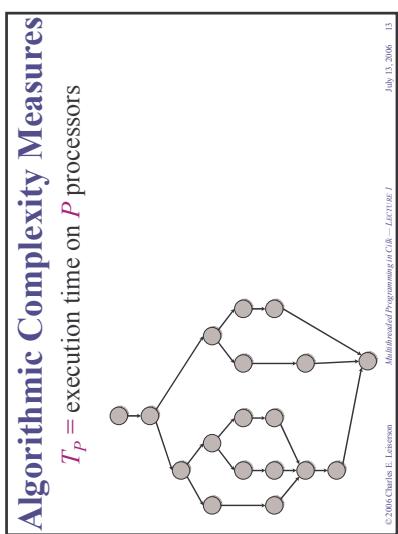- **Performance Measures**
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Algorithmic Complexity Measures

T_P = execution time on P processors

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T_1 = *work*

Algorithmic Complexity Measures

T_P = execution time on P processors

T_1 = *work*

T_∞ = *span* *

* Also called *critical-path length* or *computational depth*.

Algorithmic Complexity Measures

T_P = execution time on P processors

T_1 = *work*

T_∞ = *span* *

LOWER BOUNDS
- $T_P \geq T_1/P$
- $T_P \geq T_\infty$

* Also called *critical-path length* or *computational depth*.

Speedup

Definition: T_1/T_P = *speedup* on P processors.

If $T_1/T_P = \Theta(P) \leq P$, we have *linear speedup*;
= P, we have *perfect linear speedup*;
> P, we have *superlinear speedup*,

which is not possible in our model, because of the lower bound $T_P \geq T_1/P$.

Parallelism

Because we have the lower bound $T_P \geq T_\infty$, the maximum possible speedup given T_1 and T_∞ is

T_1/T_∞ = *parallelism*

= the average amount of work per step along the span.

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Example: `fib(4)`

Assume for simplicity that each Cilk thread in `fib()` takes unit time to execute.

Work: $T_1 = 17$
Span: $T_\infty = 8$

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Example: `fib(4)`

Assume for simplicity that each Cilk thread in `fib()` takes unit time to execute.

Work: $T_1 = 17$
Span: $T_\infty = 8$
Parallelism: $T_1/T_\infty = 2.125$

> *Using many more than 2 processors makes little sense.*

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Parallelizing Vector Addition

C

```
void vadd (real *A, real *B, int L, int H) {
    int i; for (i=L; i<H; i++) A[i]+=B[i];
}
```

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Parallelizing Vector Addition

C

```
void vadd (real *A, real *B, int L, int H) {
    int i; for (i=L; i<H; i++) A[i]+=B[i];
}
```

C

```
void vadd (real *A, real *B, int L, int H) {
    if (L+BASE>H) {
        int i; for (i=L; i<H; i++) A[i]+=B[i];
    } else {
        vadd (A, B, L, (L+H)/2);
        vadd (A, B, (L+H)/2, H);
    }
}
```

Parallelization strategy:
1. Convert loops to recursion.

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Parallelizing Vector Addition

C

```
void vadd (real *A, real *B, int L, int H) {
    int i; for (i=L; i<H; i++) A[i]+=B[i];
}
```

Cilk

```
void vadd (real *A, real *B, int L, int H) {
    if (L+BASE>H) {
        int i; for (i=L; i<H; i++) A[i]+=B[i];
    } else {
        spawn vadd (A, B, L, (L+H)/2);
        spawn vadd (A, B, (L+H)/2, H);
        sync;
    }
}
```

Parallelization strategy:
1. Convert loops to recursion.
2. Insert Cilk keywords.

> *Side benefit:* D&C is generally good for caches!

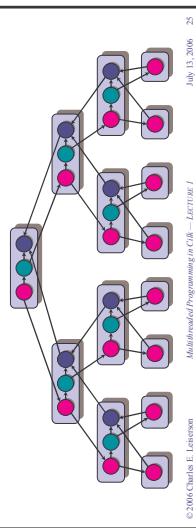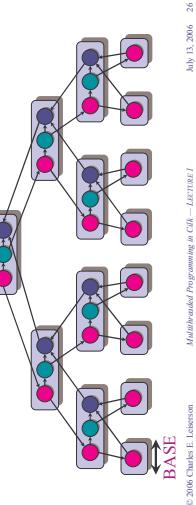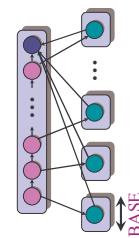*Multithreaded Programming in Cilk — LECTURE 1*

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Vector Addition

```
cilk void vadd (real *A, real *B, int L, int H) {
if (H-L+BASE>H) {
   int i; for (i=L; i<H; i++) A[i]+=B[i];
} else {
   spawn vadd (A, B, L, (L+H)/2);
   spawn vadd (A, B, (L+H)/2, H);
   sync;
}
}
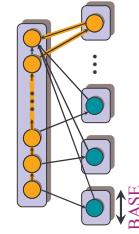```



BASE

## Vector Addition Analysis

To add two vectors of length $n$, where $\text{BASE} = \Theta(1)$:

*Work:* $T_1 = \Theta(n)$
*Span:* $T_\infty = \Theta(\lg n)$
*Parallelism:* $T_1/T_\infty = \Theta(n/\lg n)$



BASE

## Another Parallelization

**C**
```
void vadd (real *A, real *B, int L, int H) {
   int i; for (i=L; i<H; i++) A[i]+=B[i];
}
void vaddl (real *A, real *B, int L, int H) {
   int j; for (j=L; j<H; j+=BASE) {
      vadd (A, B, j, min(H,j+BASE));
   }
}
```

**Cilk**
```
cilk void vadd (real *A, real *B, int L, int H) {
   int i; for (i=L; i<H; i++) A[i]+=B[i];
}
cilk void vaddl (real *A, real *B, int L, int H) {
   int j; for (j=L; j<H; j+=BASE) {
      spawn vadd (A, B, j, min(H,j+BASE));
   }
   sync;
}
```

## Analysis



BASE

**PUNY!**

To add two vectors of length $n$, where $\text{BASE} = \Theta(1)$:

*Work:* $T_1 = \Theta(n)$
*Span:* $T_\infty = \Theta(n)$
*Parallelism:* $T_1/T_\infty = \Theta(1)$

## Optimal Choice of BASE



BASE

To add two vectors of length $n$ using an optimal choice of $\text{BASE}$ to maximize parallelism:

*Work:* $T_1 = \Theta(n)$
*Span:* $T_\infty = \Theta(\text{BASE} + n/\text{BASE})$
Choosing $\text{BASE} = \sqrt{n} \Rightarrow T_\infty = \Theta(\sqrt{n})$
*Parallelism:* $T_1/T_\infty = \Theta(\sqrt{n})$
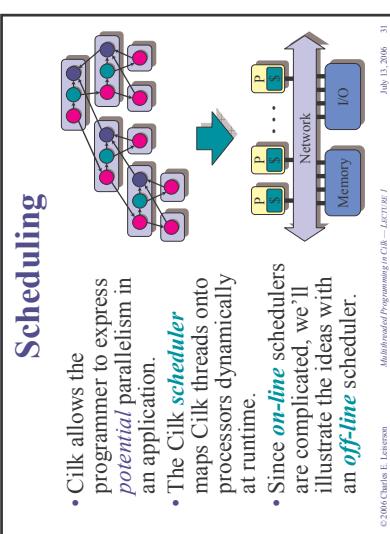
## LECTURE 1

- Basic Cilk Programming
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# Multithreaded Programming in Cilk — LECTURE 1

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## Scheduling

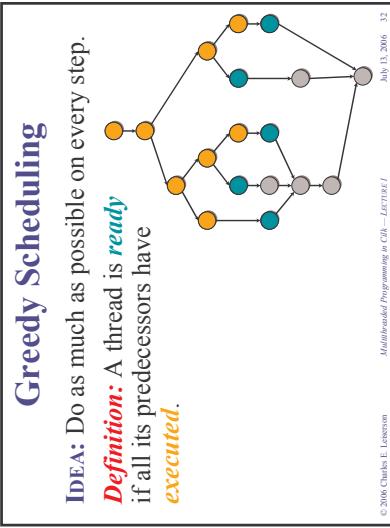- Cilk allows the programmer to express *potential* parallelism in an application.
- The Cilk *scheduler* maps Cilk threads onto processors dynamically at runtime.
- Since *on-line* schedulers are complicated, we'll illustrate the ideas with an *off-line* scheduler.

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## Greedy Scheduling

**IDEA:** Do as much as possible on every step.

*Definition:* A thread is *ready* if all its predecessors have *executed*.

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## Greedy Scheduling

**IDEA:** Do as much as possible on every step.

*Definition:* A thread is *ready* if all its predecessors have *executed*.

*Complete step*
- $\geq P$ threads ready.
- Run any $P$.

$P = 3$

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---

## Greedy Scheduling

**IDEA:** Do as much as possible on every step.

*Definition:* A thread is *ready* if all its predecessors have *executed*.

*Complete step*
- $\geq P$ threads ready.
- Run any $P$.

*Incomplete step*
- $< P$ threads ready.
- Run all of them.

$P = 3$

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## Greedy-Scheduling Theorem

*Theorem* [Graham '68 & Brent '75]: Any greedy scheduler achieves

$$T_P \leq T_1/P + T_\infty.$$

$P = 3$

*Proof.*
- # complete steps $\leq T_1/P$, since each complete step performs $P$ work.
- # incomplete steps $\leq T_\infty$, since each incomplete step reduces the span of the unexecuted dag by 1. ■

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## Optimality of Greedy

*Corollary.* Any greedy scheduler achieves within a factor of **2** of optimal.

*Proof.* Let $T_P^*$ be the execution time produced by the optimal scheduler.

Since $T_P^* \geq \max\{T_1/P, T_\infty\}$ (lower bounds), we have

$$T_P \leq T_1/P + T_\infty$$
$$\leq 2 \cdot \max\{T_1/P, T_\infty\}$$
$$\leq 2 T_P^* \ . \ \blacksquare$$

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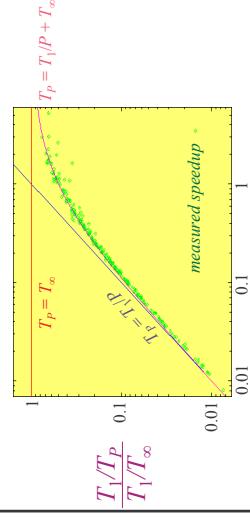# Multithreaded Programming in Cilk — LECTURE 1

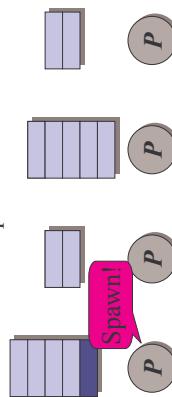*July 13, 2006*

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## LECTURE 1

- **Basic Cilk Programming**
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- **Conclusion**

---

## Cilk Performance

- Cilk's "work-stealing" scheduler achieves expected time
  - $T_P = T_1/P + O(T_\infty)$ (provably);
  - $T_P \approx T_1/P + T_\infty$ time (empirically).
- Near-perfect linear speedup if $P \ll T_1/T_\infty$.
- Instrumentation in Cilk allows the user to determine accurate measures of $T_1$ and $T_\infty$.
- The average cost of a **spawn** in Cilk-5 is only 2–6 times the cost of an ordinary C function call, depending on the platform.

---

## Linear Speedup

***Corollary.*** Any greedy scheduler achieves near-perfect linear speedup whenever $P \ll T_1/T_\infty$.

*Proof.* Since $P \ll T_1/T_\infty$ is equivalent to $T_\infty \ll T_1/P$, the Greedy Scheduling Theorem gives us

$$T_P \le T_1/P + T_\infty$$
$$\approx T_1/P.$$

Thus, the speedup is $T_1/T_P \approx P$. ∎

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## Developing ★Socrates

- For the competition, ★Socrates was to run on a 512-processor Connection Machine Model CM5 supercomputer at the University of Illinois.
- The developers had easy access to a similar 32-processor CM5 at MIT.
- One of the developers proposed a change to the program that produced a speedup of over 20% on the MIT machine.
- After a back-of-the-envelope calculation, the proposed "improvement" was rejected!

---

## ★Socrates Normalized Speedup



$$\frac{T_1/T_P}{T_1/T_\infty}$$

$$\frac{P}{T_1/T_\infty}$$

$T_P = T_\infty$

$T_P = T_1/P + T_\infty$

$T_P = T_1/P$

*measured speedup*

---

## Cilk Chess Programs

- ★***Socrates*** placed 3rd in the 1994 International Computer Chess Championship running on NCSA's 512-node Connection Machine CM5.
- ★***Socrates 2.0*** took 2nd place in the 1995 World Computer Chess Championship running on Sandia National Labs' 1824-node Intel Paragon.
- ***Cilkchess*** placed 1st in the 1996 Dutch Open running on a 12-processor Sun Enterprise 5000. It placed 2nd in 1997 and 1998 running on Boston University's 64-processor SGI Origin 2000.
- ***Cilkchess*** tied for 3rd in the 1999 WCCC running on NASA's 256-node SGI Origin 2000.

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## ★ Socrates Speedup Paradox

**Original program** | **Proposed program**

$T_{32} = 65$ seconds | $T'_{32} = 40$ seconds

$$T_P \approx T_1/P + T_\infty$$

$T_1 = 2048$ seconds | $T'_1 = 1024$ seconds
$T_\infty = 1$ second | $T'_\infty = 8$ seconds

$T_{32} = 2048/32 + 1$ | $T'_{32} = 1024/32 + 8$
$= 65$ seconds | $= 40$ seconds

$T_{512} = 2048/512 + 1$ | $T'_{512} = 1024/512 + 8$
$= 5$ seconds | $= 10$ seconds

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## Lesson

**Work** and **span** can predict performance on large machines better than running times on small machines can.

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## LECTURE 1

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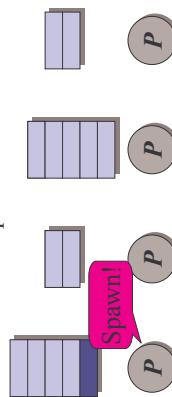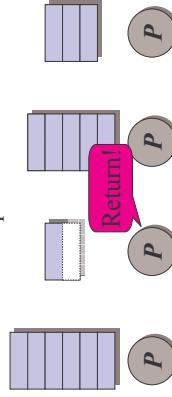*Multithreaded Programming in Cilk — LECTURE 1* July 13, 2006  45

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## Cilk's Work-Stealing Scheduler

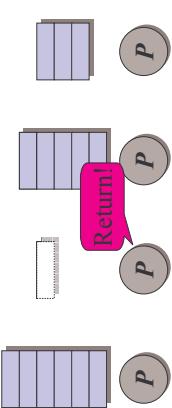Each processor maintains a *work deque* of ready threads, and it manipulates the bottom of the deque like a stack.



Spawn!

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## Cilk's Work-Stealing Scheduler

Each processor maintains a *work deque* of ready threads, and it manipulates the bottom of the deque like a stack.



Spawn!   Spawn!

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## Cilk's Work-Stealing Scheduler

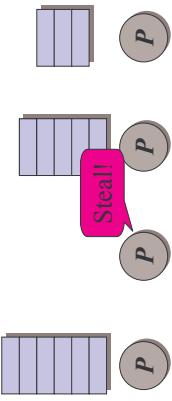Each processor maintains a *work deque* of ready threads, and it manipulates the bottom of the deque like a stack.



Return!

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## Cilk's Work-Stealing Scheduler

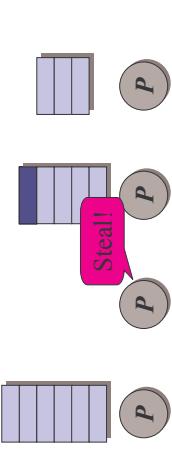Each processor maintains a *work deque* of ready threads, and it manipulates the bottom of the deque like a stack.

Return!

When a processor runs out of work, it *steals* a thread from the top of a *random* victim's deque.

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## Cilk's Work-Stealing Scheduler

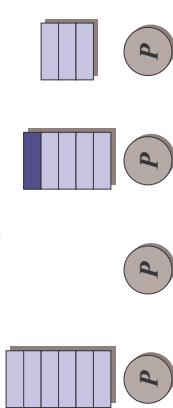Each processor maintains a *work deque* of ready threads, and it manipulates the bottom of the deque like a stack.

Steal!

When a processor runs out of work, it *steals* a thread from the top of a *random* victim's deque.

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## Cilk's Work-Stealing Scheduler

Each processor maintains a *work deque* of ready threads, and it manipulates the bottom of the deque like a stack.

Steal!

When a processor runs out of work, it *steals* a thread from the top of a *random* victim's deque.

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## Cilk's Work-Stealing Scheduler

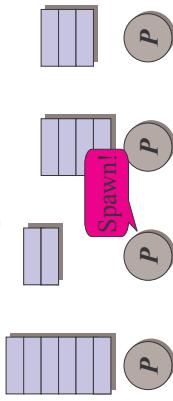Each processor maintains a *work deque* of ready threads, and it manipulates the bottom of the deque like a stack.

When a processor runs out of work, it *steals* a thread from the top of a *random* victim's deque.

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## Cilk's Work-Stealing Scheduler

Each processor maintains a *work deque* of ready threads, and it manipulates the bottom of the deque like a stack.

Spawn!

When a processor runs out of work, it *steals* a thread from the top of a *random* victim's deque.

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## Performance of Work-Stealing

*Theorem*: Cilk's work-stealing scheduler achieves an expected running time of

$$T_P \leq T_1/P + O(T_\infty)$$

on $P$ processors.

*Pseudoproof*. A processor is either *working* or *stealing*. The total time all processors spend working is $T_1$. Each steal has a $1/P$ chance of reducing the span by 1. Thus, the expected cost of all steals is $O(PT_\infty)$. Since there are $P$ processors, the expected time is

$$(T_1 + O(PT_\infty))/P = T_1/P + O(T_\infty) \ . \ \blacksquare$$

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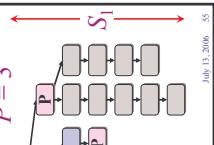
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*July 13, 2006*

## Space Bounds

***Theorem.*** Let $S_1$ be the stack space required by a serial execution of a Cilk program. Then, the space required by a $P$-processor execution is at most $S_P \leq PS_1$.

*Proof* (by induction). The work-stealing algorithm maintains the ***busy-leaves** property: every extant procedure frame with no extant descendents has a processor working on it.* ∎
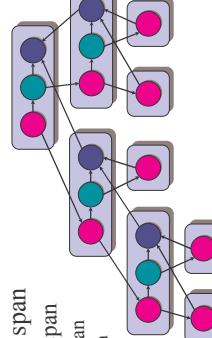
$P = 3$

$S_1$

## Linguistic Implications

Code like the following executes properly without any risk of blowing out memory:

```
for (i=1; i<1000000000; i++) {
    spawn foo(i);
}
sync;
```

MORAL
Better to steal parents than children!

LECTURE 1

- **Basic Cilk Programming**
- **Performance Measures**
- **Parallelizing Vector Addition**
- **Scheduling Theory**
- **A Chess Lesson**
- **Cilk's Scheduler**
- **Conclusion**

Key Ideas

- Cilk is simple: `cilk, spawn, sync`
- Recursion, recursion, recursion, …
- Work & span
- Work & span
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Minicourse Outline

- **LECTURE 1**
  Basic Cilk programming: Cilk keywords, performance measures, scheduling.
- **LECTURE 2**
  Analysis of Cilk algorithms: matrix multiplication, sorting, tableau construction.
- **LABORATORY**
  Programming matrix multiplication in Cilk
  — Dr. Bradley C. Kuszmaul
- **LECTURE 3**
  Advanced Cilk programming: speculative computing, mutual exclusion, race detection.

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