Scalable Defect Detection

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Part II High-Quality Scalable Checking using modular path-sensitive analysis

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Secret Sauce for a Practical Checker

Keys to high-quality scalable checkers

- Scalability: checking each function in isolation
- Quality: path sensitivity and defect prioritization

Approach proven by our experience at Microsoft

- espX: buffer-overrun checker, widely deployed and used to get 20,000+ bugs found and fixed
- μSpaCE: checker-building SDK, used by nonexperts to build domain-rule-enforcing checkers

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Scalability and Quality Overview

Scalability: Inter-Procedural Analysis?

Lecture 1 (by Manuvir): scalable inter-procedural analysis is possible, with

- Good Techniques: summarization, etc.
- Constraints on problems: finite automata, etc.

But

- Intractable for complex states (buffer overrun).
- Mismatch with the modular reasoning by devs.
 - "If an error is detected, who to blame"

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Linear Scalability by Modular Analysis

If we can afford to analyze each function in isolation

- Scales up linearly in # of functions and scales out
- Allows using complex states for accuracy But it's a big "if".
- For example, is this function safe?
 void f(int *buf, size_t n)
 { for (size_t i=0; i <= n; i++) buf[i] = 0; }
- Modular analysis requires specifications of the usage context (e.g., "buf has n elements").

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Assumption: specification possible

- "Did you say specifications?"
 - Isn't it a pipe dream to design practical spec langs?
 - Who is going to add specs to millions of functions?
- This is the subject of Lecture 3 on SAL (by Dan)
- For now, assume functions come equipped with necessary specifications of contexts.
 - Say "void f(int *buf, size_t n)" → "void f(int<n> *buf, size_t n)"
- So we can discuss modular checking in full detail.

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Quality: The measures

- Accurate: fix rate (% bugs fixed), false positive rate (% of reported bugs deemed noise)
 - Dev's perspective: frustrated with bogus issues.
- Comprehensive: validation rate (% of safe code), false negative rate (% of missed issues)
 - Exec's perspective: measure of coverage/progress.
- Clear and Actionable: easy to understand the reported defects and take appropriate actions

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Quality Measures: Historical Perspective at Microsoft

- · Early years
 - Bugs found by static analysis met with excitement
 - Accuracy is the obvious tool quality for devs
- · After a few years of worm-induced news
 - "how many bugs are left?"
 - Measure of coverage calls for comprehensive validation
- Use of symbolic abstraction improved coverage
 - "I can't understand what this message is saying."
 - "There are so many issues and so little time left."
 - Messages need to be clear and prioritized

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Achieving Quality

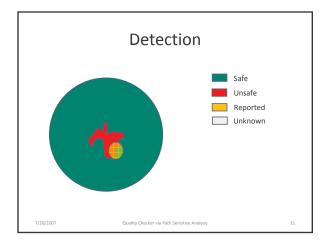
Clarity for developers to take action

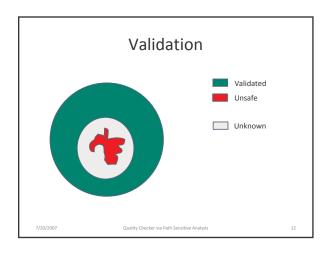
• Using path-sensitive analysis instead of data flow analysis (since devs reason with paths)

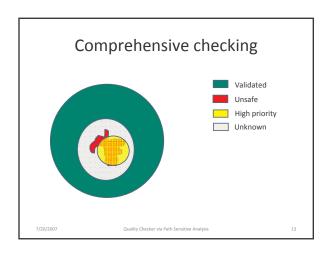
Conflicting Goals: (Accurate) defect detection vs (comprehensive) validation?

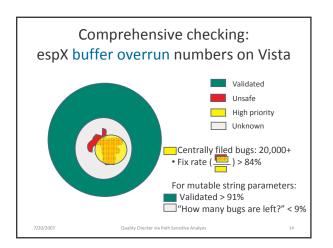
• Both: use comprehensive validation as a basis, and then expose defects through prioritization

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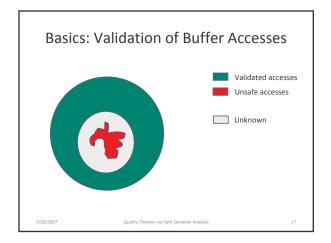




espX: Buffer Overrun Checker

Outline of this section of talk

- Basics of a buffer-overrun checker
- Prior Art: merge-based dataflow analysis
- Our Approach: path-sensitive analysis
- Warning bucketing for prioritization



```
Example 1

BYTE<n> *Alloc(size_t n);
void FillRects(RECT<n> *r, size_t n);
void FillPoints(POINT<n> *p, size_t n);

void Fill(unsigned int r, unsigned int p)
{

BYTE *buf = Alloc(r * sizeof(RECT) + p * sizeof(POINT));
FillRects((RECT *)buf, r);
buf += r * sizeof(RECT);
FillPoints((POINT *)buf, p));
}

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```

"Instrumenting" the Program

BYTE *buf = Alloc(r * sizeof(RECT) + p * sizeof(POINT)); assume: offset(buf) = 0 \square

BYTE<n> *Alloc(size_t n);

 $bcap(buf) = 16 \times r + 8 \times p$ assert: offset(buf) + 16 \times r \leq bcap(buf)

FillRects(RECT<n> *r, size_t n);

 $FillRects((RECT\ *)buf,\ r);$

buf += r * sizeof(RECT);

assert: offset(buf) + $8 \times p \le bcap(buf)$ FillPoints((POINT *)buf, p): FillPoints(POINT<n> *p, size_t n);

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Analysis of Example 1

BYTE *buf = Alloc(r * sizeof(RECT) + p * sizeof(POINT));

assume: offset(buf) = $0 \square$ bcap(buf) = $16 \times r + 8 \times p$

 $bcap(buf) = 16 \times r + 8 \times p$ assert: offset(buf) + 16 \times r \leq bcap(buf)
FillRects((RECT *)buf, r);

buf += r * sizeof(RECT);

assert: offset(buf) + $8 \times p \le bcap(buf)$ FillPoints((POINT *)buf, p); $\{r \ge 0; p \ge 0\}$

≤ bcap(buf)] PASS

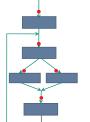
{bcap(buf) = $16 \times r + 8 \times p$; offset(buf) = 0; $r \ge 0$; $p \ge 0$ } [offset(buf) + $16 \times r = 16 \times r$

 $\begin{aligned} &\{\text{bcap(buf)} = 16 \times r + 8 \times p; \\ & \textbf{offset(buf)} = 16 \times r; \ r \geq 0; \ p \geq 0\} \\ &\{\text{loffset(buf)} + 8 \times p = \\ &16 \times r + 8 \times p \leq \ \text{bcap(buf)} \} \end{aligned}$

Need symbolic state tracking + linear integer theorem prover

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Dataflow Analysis



Given flow graph (V, E)

Task: find invariants at CFG-nodes

Find a map $A: V \rightarrow Abs$ stable under $T: E \times Abs \rightarrow Abs$

Abs: lattice of abstract values Stability condition: $A(v) = \bigcup \{ T(e, A(u)) : e = (u, v) \in E \}$

or $A = \tilde{T}(A)$ is a fixed-point of \tilde{T} If T monotone, Abs complete, then least $A = \bigsqcup \{\tilde{T}^i(\bot): i = 0, ...\}$.

This terminates if Abs finite in height.

Quality (Work-list algorithm used in practice.

Dataflow Analysis for Buffer Overruns [Dor et al:PLDI 2003]

To track the symbolic states, use a dataflow analysis

- Abs = Set of Linear Inequality Constraints
- T : suitably abstracted from concrete semantics But what about the join operator?
- I.e., how do you merge two sets of linear constraints into another set of linear constraints (that is implied by both of them)?
- Answer: Polyhedra (Cousot/Halbwachs:POPL78)

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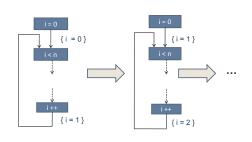
The Lattice of Polyhedra

- Geometric Interpretation:
 - One linear inequality gives a half-space
 - A set of linear inequalities is a (maybe-not-closed) convex polyhedron (n-dimensional polygon)
- Join-operator needs to find the smallest enclosing polyhedron (convex hull problem)
- · Algorithm involves lots of linear programming
- infinite-height lattice: termination for loops?

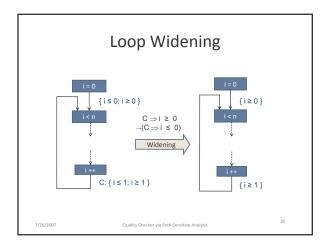
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What about Loops?



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Handling loops

- Use a loop widening algorithm to ensure that the analysis terminates
 - Widening operator: Weaken the constraints along a back edge of a loop in a way that ensures that finite number of such weakenings is sufficient
 - Mathematically, any chain formed by repeated application of the widening operator is finite.

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Issues with Polyhedra

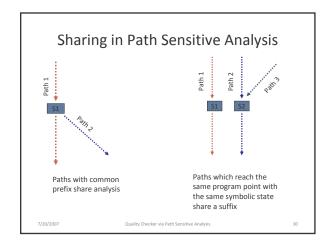
- Complexity (implementation & cost)
- Several restricted version proposed and used:
 - Octagons (at most two variables; coefficients 1, -1)
 - Arbitrary predetermined shapes.
- Inaccuracy
 - The convex hull won't be accurate closure
 - Real-numbered coefficients would appear
 - An approximation for Integer Linear Constraints

Bigger issue: feedback to developer

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Example 2 BYTE<size>*Alloc(size_t size); void StringCopy(wchar_t<n>*dest, const wchar_t {null-terminated} *src, size_t n); void ProcessString(wchar_t *str) { wchar_t buf[100]; wchar_t *tmp = &buf; int len = wcslen(str) + 1; if (len > 100) tmp = (wchar_t *)Alloc(len); StringCopy(tmp, str, len); ... } {bcap(tmp) = 200; len ≤ 100} vs {bcap (tmp) = len; len > 100} 7/20/2007 Quality Checker via Path Sensitive Analysis

Example 2 with Polyhedra • Merging {bcap(tmp) = 200; len ≤ 100} and {bcap(tmp) = len; len > 100} • That is: bcap(tmp) ≥ len bcap(tmp) | len ≥ 200 bcap(tmp) ≥ len+200 • Obscure message to devs Need path-based analysis: "overflow when len ≥ 100" 100 200 len 7/20/2007 Quality Checker via Path Sensitive Analysis 29



Path-Sensitive Dataflow Analysis

- In its simplest form, path-sensitive analysis can be characterized as a dataflow analysis
- Find A: $V \rightarrow Set(state)$ using t: E x state \rightarrow state
- *T: Set(state)* → *Set(state)* is the point-wise lifted version of *t*, using set-union.
- Set(state) is a complete lattice; T is monotone
- But *Set(state)* is infinite in height when the universe of states is infinite.

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Widening in Path-Sensitive Analysis

- Issue: We share paths only when the symbolic states are the same at a node; but loops induce infinite number of states.
- "Widening? But what state to widen against?"
- Idea: at back edge, widen against the path itself
- Solution: extend the state to record the pathhistory of states at each loop entry node.
- WidenedState = LoopNestingLevel → State
 [s₁, s₂, s₃]: state is s₃ now, and was s_i at loop level
- · Exercise: work out the detail

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Fast Theorem Prover for Integer Linear Inequalities?

- Not asking for: constraint solver, completeness
- Observation 1: developers reasoning about linear constraints in a simple way; often: a proof is just a linear combination with small integer coefficients.
- Observation 2: difference constraint theorem prover is easy to construct. [CLR:alg-textbook]
- Exercise: figure out an algorithm.

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Elements of the checker

- Symbolic state tracking with linear inequalities
 - Path sensitive analysis
 - Path sensitive loop widening
- Fast linear integer theorem prover

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Defect Bucketing/Prioritization Validated Unsafe High priority Unknown

Example 1 – provable error

if (CanProve(buffer index < buffer size))
 Validated Access</pre>

else

if (CanProve(buffer index >= buffer size))
 Provable Error
else

Possible Error

 $\bullet \;\;$ e.g. passing byte count instead of element count

wcscpy_s(buf,sizeof(buf),s); espX Warning 26000

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int glob[BUF_SIZE]; bool read(int i, int *val) { if (i > BUF_SIZE) // Off by one return false; assert: i < BUF_SIZE *val = glob[i]; ... espX Warning 26014: Cannot prove: i < BUF_SIZE Can prove: i < BUF_SIZE + 1 e.g. MS01-033(Code Red), MS04-036(NNTP), MS04-035(SMTP)</pre>

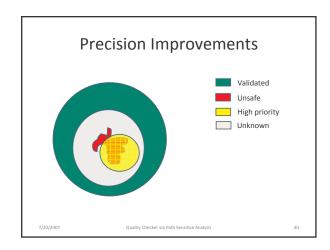
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Warning bucketing criteria

- Are heuristics based on observations of common coding mistakes
- Are semantic, not syntactic, in nature
 - Makes them robust
- Validated by security bulletin bug data and Watson crash data

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void StripSpaces(char<n> *dest, char *src, size_t n) { while (*src != 0 && n > 1) { assume: n > 1 if (*src != '') { assert: offset(dest) < n_0 *dest++ = *src; n--; } src++; } *dest = '\0'; } espX deduces offset(dest) and n are synchronized variables in the loop

Combining Theorem Provers • Example: uuencode into 6-bit ASCIIs 10131010 0110010 00111001 001000 11110101 • void uuencode(BYTE<n>*src, BYTE<(n+2)/3*4>*dest, size_t n) (Real spec added by a developer to real code) • A second layer of theorem prover to uninterpreted operations, integer divisions, modular arithmetic, bitwise operations & etc.

espX Summary

- espX have made comprehensive defect detection a reality for buffers
 - Tens of thousands of bugs found and fixed
 - "How many bugs are left?"
 - < 9% for mutable string buffers in Vista
 - Specifications also important (Details in Lecture 3)
- · Achieved using
 - Modular Path-sensitive analysis
 - Careful warning bucketing and prioritization
 - Assortment of precision-refinement techniques

Devs want to build good checkers, too

- Developers who are domain experts often want to enforce certain domain-specific rules
- Encouraged by our work, they want to go static
- E.g.: Project Goldmine (Internationalization)

```
void IssueMessage()
  ::MessageBox(NULL,
                                                      Hard-coded strings
passed to user facing API
        L"Failed to load file", <
        MB_ERROR | MB_OK);
```

Developer-Generated Analyses: μSpaCE

(Or Better: You Checker

How Do We Share Our Expertise?

- · We understand static analysis well, but we can't solve problems for all domains
- MS solution: an SDK for domain experts to build path-sensitive dataflow analysis
- Challenge: intelligible explanation, i.e., without lattice, monotone function, join, etc.
- · Our explanation: based on "Path Iteration"

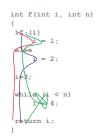
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Path Iteration

- Get set of paths; traverse them separately
- Simulation-style code:

```
For all paths p.
   For all edges e in p.
```

- Limitation:
 - Cannot have full coverage
 - No sharing of analysis across paths



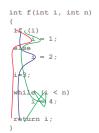
Path Iteration

- Get set of paths; traverse them separately
- Explicit simulation state:



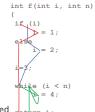
· Benefit of abstraction

- Under-the-hood improvements



Path-Sensitive Analysis

- Define transfer function with explicit abstract state
- The $\mu SpaCE$ engine maintains
 - A state set pr. node
 - Reuses path computations
 - Covers state space 100%



• The fine print:

- State domain needs to be finite
- Or else widening operator needed return i;

µSpaCE SDK for Building Checks

- SDK: a concise core (with virtual transfer functions) + oracles (memory model, spec semantics, etc.)
- Multiple clients in one year
 - Goldmine (C/C++/.NET): intl. checker & meta data gen.
 - espC (C/C++): concurrency checker
 - iCatcher (.NET): cross-site scripting checker for ASP.NET
 - NullPtr (C/C++/.NET): spec-based null-ptr checker
- · All these clients have found real bugs; they are getting deployed company wide

Summary

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- Scalability: checking each function in isolation
- Quality: path sensitivity and defect prioritization

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Exercises & Recommended Readings

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http://www.microsoft.com/cse http://research.microsoft.com/users/zhey

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