

Resource Analysis: Lecture 2

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1 Resource Monoid

We define the resource monoid for the rule described in the previous lecture.

$$(q, q').(p, p') = \begin{cases} (q + p - q', p'), & \dots \quad q' \leq p \\ (q, p' + q' - p), & \dots \quad q' \geq p \end{cases}$$

2 Language Constructs

2.1 Type System

We consider following type system to bound the resources.

$$\begin{aligned} \tau ::= & \text{unit} \\ & | \tau_1 \rightarrow \tau_2 \\ & | L(\tau) \quad \dots (\text{List}) \end{aligned}$$

2.2 Expressions in the language :

$$\begin{aligned} e ::= & \mathbf{nil}\{\tau\} & [] \\ & | \mathbf{cons}(e_1; e_2) & e_1 :: e_2 \\ & | \mathbf{matL}(e; e_1; x_1, x_2.e_2) & \text{match } e \text{ with } [] \leftrightarrow e_1, x_1 :: x_2 \rightarrow e_2 \\ & | \mathbf{tick}\{q\}(e) & \text{tick } q \text{ in } e \dots (q \in \mathbb{Q}) \\ & | \mathbf{fix}\{\tau\}(x.e) & \text{fix } x : \tau \text{ as } e \end{aligned}$$

User inputs ticks expression to denote the number of resources consumed.

2.3 Values

$$\frac{}{\mathbf{nil \ val}} \quad \frac{e_1 \ \mathbf{val} \quad e_2 \ \mathbf{val}}{\mathbf{cons}(e_1; e_2) \ \mathbf{val}}$$

2.4 Cost Dynamics

$$\langle e, q \rangle \mapsto \langle e', q' \rangle \quad \dots \cdot q, q' \geq 0$$

Reads as “with q available resources, e evaluates to e' and after evaluation, q' resources are available”.

2.5 Dynamic Rules

1.
$$\frac{q - p \geq 0}{\langle \mathbf{tick}\{p\}(e), q \rangle \mapsto \langle e, q - p \rangle}$$
2.
$$\frac{\langle e, q \rangle \mapsto \langle e', q' \rangle}{\langle \mathbf{matL}(e; e_1; x_1, x_2.e_2), q \rangle \mapsto \langle \mathbf{matL}(e'; e_1; x_1, x_2.e_2), q' \rangle}$$
3.
$$\frac{}{\langle \mathbf{matL}(\mathbf{nil}; e_1; x_1, x_2.e_2), q \rangle \mapsto \langle e_1, q \rangle}$$
4.
$$\frac{e'_1 \mathbf{val} \quad e'_2 \mathbf{val}}{\langle \mathbf{matL}(\mathbf{cons}(e'_1, e'_2); e_1; x_1 \cdot x_2, e_2), q \rangle \mapsto \langle [e'_1/x_1, e'_2/x_2]e_2, q \rangle}$$

2.6 Static Rules

1.
$$\frac{\Gamma, x: \tau \vdash e: \tau}{\Gamma \vdash \mathbf{fix}\{\tau\}(x.e): \tau}$$
2.
$$\frac{\Gamma \vdash e: \tau}{\Gamma: \mathbf{tick}\{q\}(e): \tau}$$

2.7 Observations

For the above calculus we can prove the following type safety theorems:

Proposition 1 (Preservation). *If $e: \tau$ and $\langle e, q \rangle \mapsto \langle e', q' \rangle$, then $e': \tau$.*

Proposition 2 (Progress). *Suppose $\langle \mathbf{tick}\{1\}(\langle \rangle), 0 \not\mapsto e \rangle$. If $e: \tau$, then there either $e \mathbf{val}$, or there exists q such that $\langle e, q \rangle \mapsto \langle e', q' \rangle$ for some e', q' .*

Consider the following example:

Example 3. Define id as

$$id = \mathbf{fix} \, id : L(\mathbf{unit}) \rightarrow L(\mathbf{unit}) \text{ as } \lambda(x : L(\mathbf{unit})) \text{ match } x \text{ with } [] \mapsto [] \mid y :: ys \mapsto \mathbf{tick} \, 2 \text{ in } y :: id(ys)$$

and let $v_n = \langle \rangle :: \dots :: \langle \rangle :: []$, where $\langle \rangle$ is concatenated to itself n times. Then the question is how many resources q do we need to get $\langle id, \langle v_n \rangle, q \rangle \mapsto \langle v_n, 0 \rangle$. With some calculations, we can see that for $q = 2n$:

$$\langle id, \langle v_n \rangle, 2n \rangle \mapsto \langle v_n, 0 \rangle$$

Our next goal is to do analysis in the above example with a type system. The idea is to have types that carry potentials that has to be used to pay for ticks. We introduce type-based amortized resource analysis in the next section to achieve this goal.

3 Type-based Amortized Resource Analysis

3.1 Type System

We define types τ and context Γ as follows:

$$A, B ::= \text{pot}(\tau, q) \quad \langle \tau, q \rangle$$

$$\begin{array}{l} \tau ::= \text{arr}(A, B) \quad \tau \xrightarrow{q, q'} \tau' \quad \text{where } A = \langle \tau, q \rangle, B = \langle \tau', q' \rangle \\ \quad | L(A) \quad L^q(\tau) \quad \text{where } A = \langle \tau, q \rangle \\ \quad | \text{unit} \quad 1 \end{array}$$

$$\Gamma ::= \cdot \mid x : \tau$$

As illustrated in the following example, we have a set of annotations for each function in this system.

Example 4. In the expression

$$\lambda(x : L(\text{unit}))id(id(x)) : L^4(\text{unit}) \xrightarrow{0/0} L^0(\text{unit}),$$

function id has two different types: $id : L^2(\text{unit}) \xrightarrow{0/0} L^0(\text{unit})$ and $id : L^4(\text{unit}) \xrightarrow{0/0} L^2(\text{unit})$.

Definition 5 (Potential). For arbitrary expression $v : \tau$, its *potential* $\Phi(v : \tau)$ is defined as follows:

- $\Phi(v : \text{unit}) = 0$
- $\Phi(\text{lam}\{\tau\}(x : e) : A \rightarrow B) = 0$
- $\Phi(\text{cons}(v_1, v_2) : L(A)) = \Phi(v_1 : A) \rightarrow \Phi(v_2 : L(A))$.
- $\Phi(v : \langle \tau, q \rangle) = q + \Phi(v, \tau)$

Example 6. The following hold according to the definition above:

- $\Phi(\langle \rangle : \langle \text{unit}, 10 \rangle) = 10$
- $\Phi(\langle \rangle :: \langle \rangle :: [] : L^5(\text{unit})) = 10$
- $\Phi(a_1 :: \dots :: a_n :: [] : L^1(\tau)) = q.n + \sum_{1 \leq i \leq n} \Phi(a_i : \tau)$

3.2 Type system

The type judgements are of the form $\Gamma \vdash_{q'}^q e : \tau$ meaning that under context Γ with potential q , expression e has annotated type τ and potential q' . The rules for judgements are as follows:

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$$\frac{}{x : \tau \vdash_0^0 x : \tau}$$

Note that in this rule the only thing allowed in the context is variable x , i.e. we need to consume all other things in the context. Also, context and expression potentials are restricted to 0, instead of an arbitrary q .

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$$\frac{\Gamma_1 \vdash_r^q e_1 : \tau \xrightarrow{p/q'} \tau' \quad \Gamma_2 \vdash_p^r e_2 : \tau}{\Gamma_1 \Gamma_2 \vdash_{q'}^q e_1(e_2) : \tau'}$$

The potential in Γ_1 is q and $e_1 : \tau \xrightarrow{p/q'}$ is a function with potential r . This potential can be used in Γ_2 to evaluate e_2 . The potential we have around after evaluating $e_2 : \tau$ is p and we can plug it into the function body e_1 with encoded potential p/q' . Then we are left with potential q' and $e_1(e_2) : \tau'$.

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$$\frac{\Gamma, x : \tau \vdash_p^p e : \tau' \quad |\Gamma| = \Gamma}{\Gamma \vdash_0^0 \mathbf{lam}\{\tau\}(x \cdot e) : \tau \rightarrow \tau'}$$

We write $|\tau|$ for τ in which all annotations q are replaced by 0. And $|\Gamma|$ is defined point-wise on the types. We will see by an example in the next lecture that the extra assumption $|\Gamma| = \Gamma$ assures possibility of using a function more than once.

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$$\frac{\Gamma, x : \tau \vdash_0^0 e : \tau' \quad |\tau| = \tau \quad |\Gamma| = \Gamma}{\Gamma \vdash_0^0 \mathbf{fix}\{\tau\}(x \cdot e) : \tau'}$$