

# Reasoning about Probabilistic Programs

Oregon PL Summer School 2021

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## Day 1: Introducing Probabilistic Programs

- ▶ Motivations and key questions
- ▶ Mathematical preliminaries

## Day 2: First-Order Programs 1

- ▶ Probabilistic While language, monadic semantics
- ▶ Weakest pre-expectation calculus

## Day 3: First-Order Programs 2

- ▶ Probabilistic While language, transformer semantics
- ▶ Probabilistic separation logic

## Day 4: Higher-Order Programs

- ▶ Type system: probability monad
- ▶ Type system: probabilistic PCF

# Please ask questions!

## OPLSS Slack: #probabilistic

- ▶ I will check in periodically for offline questions

## Zoom chat/raise hand

- ▶ Thanks to Breandan Considine for moderating!

## We don't have to get through everything

- ▶ We will have to skip over many topics, anyways

## Requests are welcome!

- ▶ Tell me if you're curious about something not on the menu

# Probabilistic Programs Are Everywhere!

# Executable code: Randomized Algorithms

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## Better performance in exchange for chance of failure

- ▶ Check if  $n \times n$  matrices  $A \cdot B = C$ :  $O(n^{2.37\dots})$  operations
- ▶ Freivalds' randomized algorithm:  $O(n^2)$  operations

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## Improve performance against “worst-case” inputs

- ▶ Quicksort: if input is worst-case,  $O(n^2)$  comparisons
- ▶ Randomized quicksort:  $O(n \log n)$  comparisons on average

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## Other benefits

- ▶ Randomized algorithms can be simpler to describe
- ▶ Sometimes: more efficient than deterministic algorithms



# Executable code: Security and Privacy

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- ▶ Generate secrets the adversary doesn't know
- ▶ Example: draw encryption/decryption keys randomly

## Privacy

- ▶ Add random noise to blur private data
- ▶ Example: differential privacy

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- ▶ Search a huge space of potential inputs
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- ▶ Avoid human bias in selecting testcases

## Very common strategy for testing programs

- ▶ Property-based testing (e.g., QuickCheck)
- ▶ Fuzz testing (e.g., AFL, OSS-Fuzz)

# Modeling tool: Representing Uncertainty

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Think of uncertain things as drawn from a distribution

- ▶ Example: whether a network link fails or not
- ▶ Example: tomorrow's temperature



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## Think of uncertain things as drawn from a distribution

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## Different motivation from executable code

- ▶ Aim: model some real-world data generation process
- ▶ Less important: generating data from this distribution

# Modeling tool: Fitting Empirical Data

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- ▶ Based on data collected from the world, infer parameters of the model

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## Example: learning the bias of a coin

- ▶ Boolean data generated by coin flips
- ▶ Unknown parameter: bias of the coin
- ▶ Flip coin many times, try to infer the bias

# Modeling tool: Approximate Computing

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## Computing on unreliable hardware

- ▶ Hardware operations may occasionally give wrong answer
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## Model failures as drawn from a distribution

- ▶ Run hardware many times, estimate failures rate
- ▶ Randomized program describes approximate computing

# Main Questions and Research Directions



# What to know about probabilistic programs?

## Four general categories

- ▶ Semantics
- ▶ Verification
- ▶ Automation
- ▶ Implementation

# Semantics: what do programs mean mathematically?

## Specify what programs are supposed to do

- ▶ Programs may generate complicated distributions
- ▶ Desired behavior of programs may not be obvious

## Common tools

- ▶ Denotational semantics: define program behavior using mathematical concepts from probability theory (distributions, measures, ...)
- ▶ Operational semantics: define how programs step

# Verification: how to prove programs correct?

## Design ways to prove probabilistic program properties

- ▶ Target properties can be highly mathematical, subtle
- ▶ Goal: reusable techniques to prove these properties

## Common tools

- ▶ Low-level: interactive theorem provers (e.g., Coq, Agda)
- ▶ Higher-level: type systems, Hoare logic, and custom logics

# Automation: how to analyze programs automatically?

## Prove correctness without human help

- ▶ Benefit: don't need any human expertise to run
- ▶ Drawback: less expressive than manual techniques

## Common tools

- ▶ Probabilistic model checking (e.g., PRISM, Storm)
- ▶ Abstract interpretation

# Implementation: how to run programs efficiently?

Executing a probabilistic program is not always easy

- ▶ Especially: in languages supporting **conditioning**
- ▶ Algorithmic insights to execute probabilistic programs

Common tools: sampling algorithms

- ▶ Markov Chain Monte Carlo (MCMC)
- ▶ Sequential Monte Carlo (SMC)

Important division: conditioning or not?

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## No conditioning in language

- ▶ Semantics is more straightforward
- ▶ Easier to implement; closer to executable code
- ▶ Verification and automation are more tractable

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## No conditioning in language

- ▶ Semantics is more straightforward
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## Yes conditioning in language

- ▶ Semantics is more complicated
- ▶ Difficult to implement efficiently, but useful for modeling
- ▶ Verification and automation are very difficult



Our focus, and the plan (can't cover everything!)

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## Programs **without** conditioning

- ▶ Simpler, and covers many practical applications

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## Semantics can make properties easier or harder to verify

- ▶ Probabilistic programs: several natural semantics
- ▶ Choice of semantics strongly affects verification

Verifying Probabilistic Programs

What Are the Challenges?



Traditional verification: big code, general proofs

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It computes a super-set of the possible run-time errors. ASTRÉE is designed for efficiency on large software: hundreds of thousands of lines of code are analyzed in a matter of hours, while producing very few false alarms. For example, some fly-by-wire avionics reactive control codes (70 000 and 380 000 lines respectively, the latter of a much more complex design) are analyzed in 1 h and 10 h 30' respectively on current single-CPU PCs, with *no false alarm* [1,2,9].

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**Key lessons for designing static analyses tools deployed to find bugs in hundreds of millions of lines of code.**

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**How Coverity built a bug-finding tool, and a business, around the unlimited supply of bugs in software systems.**

BY AL BESSEY, KEN BLOCK, BEN CHELF, ANDY CHOU, BRYAN FULTON, SETH HALLEM, CHARLES HENRI-GROS, ASYA KAMSKY, SCOTT MCPEAK, AND DAWSON ENGLER

## A Few Billion Lines of Code Later

# Randomized programs: small code, specialized proofs

## Small code

- ▶ Usually: on the order of 10s of lines of code
- ▶ 100-line algorithm: unthinkable (and un-analyzable)

## Specialized proofs

- ▶ Often: apply combination of known and novel techniques
- ▶ Proofs (and techniques) can be research contributions

# Simple programs, but complex program states

Programs manipulate distributions over program states

- ▶ Each state has a numeric probability
- ▶ Probabilities of different states may be totally unrelated

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## Example: program with 10 Boolean variables

- ▶ Non-probabilistic programs:  $2^{10} = 1024$  possible states
- ▶ Probabilistic programs: each state also has a probability
- ▶ 1024 possible states versus uncountably many states

Properties are fundamentally quantitative



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## Key probabilistic properties often involve...

- ▶ Probabilities of events (e.g., returning wrong result)
- ▶ Average value of randomized quantities (e.g., running time)

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## Can't just "ignore" probabilities

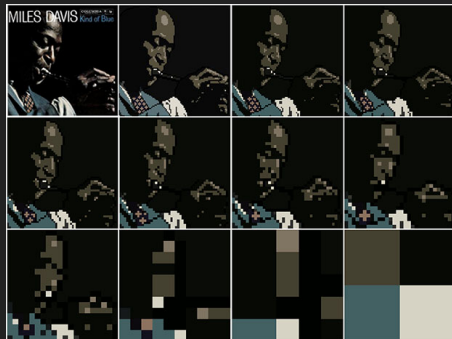
- ▶ Treat probabilities as zero or non-zero (non-determinism)
- ▶ Simplifies verification, but can't prove most properties

Needed: good abstractions for probabilistic programs

Discard unneeded aspects of a program's state/behavior

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Discard unneeded aspects of a program's state/behavior



— Andy Baio, Jay Maisel

# What do we want from these abstractions?

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## Desired features

1. Retain enough info to show target probabilistic properties
2. Be easy to establish (or at least not too difficult)
3. Behave well under program composition

# Mathematical Preliminaries



# Distributions and sub-distributions

**Distribution over  $A$  assigns a probability to each  $a \in A$**

Let  $A$  be a countable set. A (discrete) **distribution over  $A$** ,  $\mu \in \text{Distr}(A)$ , is a function  $\mu : A \rightarrow [0, 1]$  such that:

$$\sum_{a \in A} \mu(a) = 1.$$

**For modeling non-termination: sub-distributions**

A (discrete) **subdistribution over  $A$** ,  $\mu \in \text{SDistr}(A)$ , is a function  $\mu : A \rightarrow [0, 1]$  such that:

$$\sum_{a \in A} \mu(a) \leq 1.$$

“Missing” mass is probability of non-termination.

# Examples of distributions

## Fair coin: Flip

- ▶ Distribution over  $\mathbb{B} = \{tt, ff\}$
- ▶  $\mu(tt) = \mu(ff) \triangleq 1/2$

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## Biased coin: Flip(1/4)

- ▶ Distribution over  $\mathbb{B} = \{tt, ff\}$
- ▶  $\mu(tt) \triangleq 1/4, \mu(ff) \triangleq 3/4$

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## Biased coin: Flip(1/4)

- ▶ Distribution over  $\mathbb{B} = \{tt, ff\}$
- ▶  $\mu(tt) \triangleq 1/4, \mu(ff) \triangleq 3/4$

## Dice roll: Roll

- ▶ Distribution over  $\mathbb{N} = \{0, 1, 2, \dots\}$
- ▶  $\mu(1) = \dots = \mu(6) \triangleq 1/6$
- ▶ Otherwise:  $\mu(n) \triangleq 0$

# Notation for distributions

## Probability of a set

Let  $E \subseteq A$  be an **event**, and let  $\mu \in \text{Distr}(A)$  be a distribution. Then the **probability of  $E$  in  $\mu$**  is:

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## Expected value

Let  $\mu \in \text{Distr}(A)$  be a distribution, and  $f : A \rightarrow \mathbb{R}^+$  be a non-negative function. Then the **expected value of  $f$  in  $\mu$**  is:

$$\mathbb{E}_{x \sim \mu}[f(x)] \triangleq \sum_{x \in A} f(x) \cdot \mu(x).$$

# Operations on distributions: unit

## The simplest possible distribution

**Dirac distribution:** Probability 1 of producing a particular element, and probability 0 of producing anything else.

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## Distribution unit

Let  $a \in A$ . Then  $unit(a) \in \mathbf{Distr}(A)$  is defined to be:

$$unit(a)(x) = \begin{cases} 1 & : x = a \\ 0 & : \text{otherwise} \end{cases}$$

Why “unit”? The unit (“return”) of the distribution monad.



# Operations on distributions: map

Translate each distribution output to something else

Whenever sample  $x$ , sample  $f(x)$  instead. Transformation map  $f$  is **deterministic**: function  $A \rightarrow B$ .

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**Distribution map**

Let  $f : A \rightarrow B$ . Then  $map(f) : \text{Distr}(A) \rightarrow \text{Distr}(B)$  takes  $\mu \in \text{Distr}(A)$  to:

$$map(f)(\mu)(b) \triangleq \sum_{a \in A: f(a)=b} \mu(a)$$

Probability of  $b \in B$  is sum probability of  $a \in A$  mapping to  $b$ .

# Example: distribution map

## Swap results of a biased coin flip

- ▶ Let  $neg : \mathbb{B} \rightarrow \mathbb{B}$  map  $tt \mapsto ff$ , and  $ff \mapsto tt$ .
- ▶ Then  $\mu = map(neg)(\mathbf{Flip}(1/4))$  swaps the results of a biased coin flip.
- ▶ By definition of map:  $\mu(tt) = 3/4, \mu(ff) = 1/4$ .

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### Try this at home!

What is the distribution obtained by adding 1 to the result of a dice roll `Roll`? Compute the probabilities using map.

# Operations on distributions: bind

## Sequence two sampling instructions together

Draw a sample  $x$ , then draw a sample from a distribution  $f(x)$  depending on  $x$ . Transformation map  $f$  is **randomized**: function  $A \rightarrow \text{Distr}(B)$ .

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## Distribution bind

Let  $\mu \in \text{Distr}(A)$  and  $f : A \rightarrow \text{Distr}(B)$ . Then  $\text{bind}(\mu, f) \in \text{Distr}(B)$  is defined to be:

$$\text{bind}(\mu, f)(b) \triangleq \sum_{a \in A} \mu(a) \cdot f(a)(b)$$

## Unpacking the formula for bind

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1. Sample  $a \in A$  from  $\mu$ : probability  $\mu(a)$



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1. Sample  $a \in A$  from  $\mu$ : probability  $\mu(a)$
2. Sample  $b$  from  $f(a)$ : probability  $f(a)(b)$
3. Sum over all possible “intermediate samples”  $a \in A$

# Example: distribution bind

## Summing two dice rolls

- ▶ For  $n \in \mathbb{N}$ , let  $f(n) \in \text{Distr}(\mathbb{N})$  be the distribution of adding  $n$  to the result of a fair dice roll  $\mathbf{Roll}$ .
- ▶ Then:  $\mu = \text{bind}(\mathbf{Roll}, f)$  is the distribution of the sum of two fair dice rolls.
- ▶ Can check from definition of bind:  
$$\mu(2) = (1/6) \cdot (1/6) = 1/36$$

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## Try this at home!

- ▶ Define  $f$  in terms of distribution map.
- ▶ What if you try to define  $\mu$  with `map` instead of `bind`?

# Operations on distributions: conditioning

## Restrict a distribution to a smaller subset

Given a distribution over  $A$ , assume that the result is in  $E \subseteq A$ .  
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## Distribution conditioning

Let  $\mu \in \text{Distr}(A)$ , and  $E \subseteq A$ . Then  $\mu$  **conditioned on  $E$**  is the distribution in  $\text{Distr}(A)$  defined by:

$$(\mu \mid E)(a) \triangleq \begin{cases} \mu(a)/\mu(E) & : a \in E \\ 0 & : a \notin E \end{cases}$$

Idea: probability of  $a$  “assuming that” the result must be in  $E$ . Only makes sense if  $\mu(E)$  is not zero!

## Example: conditioning

### Rolling a dice until even number

Suppose we repeatedly roll a dice until it produces an even number. What distribution over even numbers will we get?

# Example: conditioning

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## Model as a conditional distribution

- ▶ Let  $E = \{2, 4, 6\}$
- ▶ Resulting distribution is  $\mu = (\mathbf{Roll} \mid E)$
- ▶ From definition of conditioning:  $\mu(2) = \mu(4) = \mu(6) = 1/3$

## Try this at home!

Suppose we keep rolling two dice until the sum of the dice is 6 or larger. What is the distribution of the final sum?



# Operations on distributions: convex combination

## Blending/mixing two distributions

Say we have distributions  $\mu_1, \mu_2$  over the same set. Blending the distributions: with probability  $p$ , draw something from  $\mu_1$ . Else, draw something from  $\mu_2$ .

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## Convex combination

Let  $\mu_1, \mu_2 \in \text{Distr}(A)$ , and let  $p \in [0, 1]$ . Then the **convex combination** of  $\mu_1$  and  $\mu_2$  is defined by:

$$\mu_1 \oplus_p \mu_2(a) \triangleq p \cdot \mu_1(a) + (1 - p) \cdot \mu_2(a).$$

# Example: convex combination

## Blend two biased coin flips

- ▶ Let  $\mu_1 = \mathbf{Flip}(1/4)$ ,  $\mu_2 = \mathbf{Flip}(3/4)$
- ▶ From definition of mixing,  $\mu_1 \oplus_{1/2} \mu_2$  is a fair coin  $\mathbf{Flip}$

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## Try this at home!

- ▶ Show that  $\mathbf{Flip}(r) \oplus_p \mathbf{Flip}(s) = \mathbf{Flip}(p \cdot r + (1 - p) \cdot s)$ .
- ▶ Show this relation between mixing and conditioning:

$$\mu = (\mu \mid E) \oplus_{\mu(E)} (\mu \mid \overline{E})$$

# Operations on distributions: independent product

## Distribution of two “fresh” samples

Common operation in probabilistic programming languages:  
draw a sample, and then draw another, “fresh” sample.

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Common operation in probabilistic programming languages: draw a sample, and then draw another, “fresh” sample.

## Independent product

Let  $\mu_1 \in \text{Distr}(A_1)$  and  $\mu_2 \in \text{Distr}(A_2)$ . Then the **independent product** is the distribution in  $\text{Distr}(A_1 \times A_2)$  defined by:

$$(\mu_1 \otimes \mu_2)(a_1, a_2) \triangleq \mu_1(a_1) \cdot \mu_2(a_2).$$

# Example: independent product

## Distribution of two fair coin flips

- ▶ Let  $\mu_1 = \mu_2 = \mathbf{Flip}$
- ▶ Then distribution of pair of fair coin flips is  $\mu = \mu_1 \otimes \mu_2$
- ▶ By definition, can show  $\mu(b_1, b_2) = (1/2) \cdot (1/2) = 1/4$ .

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## Try this at home!

- ▶ Show that  $unit(a_1) \otimes unit(a_2) = unit((a_1, a_2))$ .
- ▶ Can you formulate and prove an interesting property relating independent product and distribution bind?



# Our First Probabilistic Language

## Probabilistic WHILE (PWHILE)

# PWHILE by Example

## The language, in a nutshell

- ▶ Core imperative WHILE-language
- ▶ Assignment, sequencing, if-then-else, while-loops
- ▶ Main extension: a command for random sampling  $x \stackrel{\$}{\leftarrow} d$ , where  $d$  is a built-in distribution

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- ▶ Main extension: a command for random sampling  $x \stackrel{\$}{\leftarrow} d$ , where  $d$  is a built-in distribution

## Can you guess what this program does?

```
 $x \stackrel{\$}{\leftarrow} \mathbf{Roll};$   
 $y \stackrel{\$}{\leftarrow} \mathbf{Roll};$   
 $z \leftarrow x + y$ 
```

# PWHILE by Example

## Control flow can be probabilistic

- ▶ Branches can depend on random samples
- ▶ Challenge for verification: can't do a simple case analysis
- ▶ In some sense, an execution takes **both** branches

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```
choice  $\stackrel{\$}{\leftarrow}$  Flip;  
if choice then  
    res  $\stackrel{\$}{\leftarrow}$  Flip(1/4)  
else  
    res  $\stackrel{\$}{\leftarrow}$  Flip(3/4)
```

# PWHILE by Example

## Loops can also be probabilistic

- ▶ Number of iterations can be randomized
- ▶ Termination can be probabilistic

# PWHILE by Example

## Loops can also be probabilistic

- ▶ Number of iterations can be randomized
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## Can you guess what this program does?

```
 $t \leftarrow 0; stop \leftarrow ff;$   
while  $\neg stop$  do  
   $t \leftarrow t + 1;$   
   $stop \stackrel{\$}{\leftarrow} \mathbf{Flip}(1/4)$ 
```

# More formally: PWHILE expressions

## Grammar of boolean and numeric expressions

$\mathcal{E} \ni e := x \in \mathcal{X}$	(variables)
$  b \in \mathbb{B}   \mathcal{E} > \mathcal{E}   \mathcal{E} = \mathcal{E}$	(booleans)
$  n \in \mathbb{N}   \mathcal{E} + \mathcal{E}   \mathcal{E} \cdot \mathcal{E}$	(numbers)

## Basic expression language

- ▶ Expression language can be extended if needed
- ▶ Assume: programs only use well-typed expressions



# More formally: PWHILE d-expressions

## Grammar of d-expressions

$\mathcal{DE} \ni d :=$	<b>Flip</b>	(fair coin flip)
	<b>Flip</b> ( $p$ )	( $p$ -biased coin flip, $p \in [0, 1]$ )
	<b>Roll</b>	(fair dice roll)

## “Built-in” or “primitive” distributions

- ▶ Distributions can be extended if needed
- ▶ “Mathematically standard” distributions
- ▶ Distributions that can be sampled from in hardware

# More formally: PWHILE commands

## Grammar of commands

$\mathcal{C} \ni c := \text{skip}$	(do nothing)
$\mathcal{X} \leftarrow \mathcal{E}$	(assignment)
$\mathcal{X} \overset{\$}{\leftarrow} \mathcal{D}\mathcal{E}$	(sampling)
$\mathcal{C} ; \mathcal{C}$	(sequencing)
if $\mathcal{E}$ then $\mathcal{C}$ else $\mathcal{C}$	(if-then-else)
while $\mathcal{E}$ do $\mathcal{C}$	(while-loop)

## Imperative language with sampling

- ▶ Bare-bones imperative language
- ▶ Many possible extensions: procedures, pointers, etc.