



Contextual Modal Type Theory — Brigitte Pientka

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1 Notations

As discussed in the previous lecture, the following notations are used:

- $\Box A$: A is necessarily true / A is valid
- Δ : context of ‘global’ valid assumptions, ‘live forever’, $\{A_1 : \text{valid}, \dots, A_n : \text{valid}\}$
- Γ : context of ‘local’ true assumptions, ‘live here and now’, $\{A_1 : \text{true}, \dots, A_n : \text{true}\}$

2 Contextual Types

2.1 Intro to contextual types

- We’ll examine a common example from natural deduction:

$$x : A \supset B \supset C, y : A \wedge B \vdash \boxed{} : B \supset C$$

- Usually, we would like to fill the hole by applying $\text{proj}_1 B$ to A to get $B \supset C$
- However, $\boxed{}$ here is not necessarily closed
- The idea of contextual type is to pair the context (here is $x : A \supset B \supset C, y : A \wedge B$) with the conclusion (here is $B \supset C$)[1]
- Think about when we type check the following:

$$\frac{x : \text{int} \vdash \boxed{} + 1 : \text{int}}{\cdot \vdash \lambda x. \boxed{} + 1 : \text{int}} \quad (1)$$

- We know that $\boxed{}$ stands for `int` in the context of $x : \text{int}$

Types/Props $A := \dots \mid \Box(\Psi \Vdash A)$

We can read $\Psi \Vdash A$ as “pair the context Ψ with the conclusion A ”.

Terms $M := \dots \mid \text{box } (\Psi, M)$

Some possible inhabitants of $\Box$ given example 1:

- 0
 - A note: the term $\text{box } (x : \text{int}, 0)$ has type $\Box(x : \text{int} \Vdash \text{int})$
- x (because we already have that $x : \text{int}$)
- $x * x$

Takeaway: we have a typing derivation that we haven’t yet finished, represented by our $\Box$ s. Thus we refer to the conclusion to infer the contextual type.

2.2 Contextual rule rewrites

$$\begin{array}{c}
 \frac{\Delta; \Psi \vdash M : A}{\Delta; \Gamma \vdash \text{box } (\Psi, M) : \Box(\Psi \Vdash A)} \quad (\Box I) \qquad \frac{\Delta; \Gamma \vdash M : \Box(\Psi \Vdash A) \quad (\Delta, u : (\Psi \Vdash A)); \Gamma \vdash N}{\Delta; \Gamma \vdash \text{let box } u = M \text{ in } N : C} \quad (\Box E) \\
 \\
 \frac{x : A_{\text{true}} \in \Gamma}{\Delta; \Gamma \vdash x : A} \qquad \frac{u : (\Psi \Vdash A) \in \Delta \quad \Delta; \Gamma \vdash \sigma : \Psi}{\Delta; \Gamma \vdash \text{clo } (u, \sigma) : A}
 \end{array}$$

We define the relation between Ψ and Γ by providing witnesses:
in equation $\Delta; \Gamma \vdash \sigma : \Psi$,

- $\sigma = M_1/x_1, \dots, M_n/x_n$
- $\Psi = x_1 : A_1_{\text{true}}, \dots, x_n : A_n_{\text{true}}$

where $\Delta; \Gamma \vdash M_i : A_i$.

In more formal terms,

$$\frac{\Delta; \Gamma \vdash \sigma : \Psi \quad \Delta; \Gamma \vdash M : A}{\Delta; \Gamma \vdash (\sigma, M/x) : \Psi, x : A}$$

In essence, Ψ is the domain, Γ is the range, and σ is a mapping from $\Psi \longrightarrow \Gamma$. We provide instantiations for all $x \in \Psi$, then make sure that all of these instantiations make sense in Γ .

Intuitively, doesn't it make sense that $\Box(x : A, y : B \Vdash C)$ is “equivalent” to $\Box(A \supset B \supset C)$? A small derivation:

$$\frac{\frac{\frac{\Delta; x : A, y : B \vdash \dots C}{\Delta; x : A \vdash \dots B \supset C}}{\Delta; \cdot \vdash \dots : A \supset B \supset C}}{\Delta; \Gamma \vdash \dots : \Box A \supset B \supset C}$$

3 Comparing contextual and non-contextual types

3.1 Example 1: implication chains

Type: $\Box(C \supset A) \supset \Box(C \supset D \supset A)$

Term: $\lambda x : \Box(C \supset A). \text{let box } u = x \text{ in box } (\lambda y : C. \lambda x : D. u \ y)$ (where $u = C \supset A$ valid)

We can see that our `box` holds instructions followed by a function application: u applied to y .

Now using contextual types:

Type: $\Box(x' : C \Vdash A) \supset \Box(y : C, x : D \Vdash A)$

Term:

$\lambda x : \Box(x' : C \Vdash A). \text{let box } u = x \text{ in box } (y : C, x : D. \text{clo } (u, y/x'))$ (where $u = (x' : C \Vdash A)$)

In this example, we turn x 's into y 's using a closure (`clo`) instead of a function application. Closures fire much sooner than function applications, which we'll explore more in the following example.

3.2 Example 2: nth function

Rewriting our `nth` function from the previous lecture, we have type signature

$$\text{nth} : \text{int} \longrightarrow \Box(v : \text{bool_vec} \Vdash \text{bool})$$

where

$$\begin{aligned} \text{nth } 0 &= \text{box } (v : \text{bool_vec}, \text{hd } v) \\ \text{nth } (\text{suc } n) &= \text{let box } u = \text{nth } n \text{ in box } (v : \text{bool_vec}, \text{clo } (u, \text{tl } v)). \end{aligned}$$

Let's evaluate an example, `nth 2`:

$$\begin{aligned} \text{nth } 2 &\longrightarrow \text{let box } u = \text{nth } 1 \text{ in box } (v : \text{bool_vec}, \text{clo } (u, \text{tl } v/v_1)) \\ \text{nth } 1 &\longrightarrow \text{let box } u = \text{nth } 0 \text{ in box } (v : \text{bool_vec}, \text{clo } (u, \text{tl } v/v_0)) \\ &\longrightarrow \text{let box } u = \text{box } (v_0, \text{hd } v_0) \text{ in box } (v : \text{bool_vec}, \text{clo } (u, \text{tl } v/v_0)) \\ &\longrightarrow \text{box } (v, \text{clo } (\text{hd } v_0, \text{tl } v/v_0)) \\ &\longrightarrow \text{box } (v. \text{hd}(\text{tl } v)) \end{aligned}$$

We can see that our contextual-typed version is eager, thus giving us the expected answer that our lazy function-evaluated `nth` function failed to show in the previous lecture. Functions evaluate once they have all of the information; contextual types treat arguments like syntax and splice until they get the most simplified result.

- Substitution for “local” variables: $[M/x]x = M$
- Modal substitution for global variables: $\llbracket (\Psi.M)/u \rrbracket_{\text{clo}} (u, \sigma) = [\sigma]M$

One example of where this is used is in simplifying expressions like `box (fn x → x + (x + 0))`. We want our program to continue to analyze this expression, resulting in the simpler `box (fn x → x + x)`. However, the program can’t *evaluate* because we don’t have a value of x provided. Thus, we use syntax manipulation - $(x + 0)$ is itself a contextual type.

4 Another view: “quote and splice”

In the Kripke-like “quote and splice” view, we have expressions like

$$\Gamma_1; \dots; \Gamma_n \vdash M : A$$

and rules like

$$\frac{\vec{\Gamma}; \Gamma; \cdot \vdash M : A}{\vec{\Gamma}; \Gamma \vdash \Box M : \Box A}$$

$$\frac{\vec{\Gamma}; \Gamma \vdash M : \Box A}{\vec{\Gamma}; \Gamma_i; \dots; \Gamma_n \vdash \text{unbox}_n M : A}$$

The two

views are proven to be equivalent. The Kripke view is more akin to code, but the contextually-typed view is more well-behaved.

References

- [1] Aleksandar Nanevski, Frank Pfenning, and Brigitte Pientka. “Contextual modal type theory”. In: *ACM Trans. Comput. Logic* 9.3 (June 2008). ISSN: 1529-3785. DOI: [10.1145/1352582.1352591](https://doi.org/10.1145/1352582.1352591). URL: <https://doi.org/10.1145/1352582.1352591>.